A FINITE ELEMENT PREPROCESSOR FOR SAP IV AND ADINA

Adrian Earl Kibler

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THESIS

A FINITE ELEMENT PREPROCESSOR FOR SAP IV AND ADINA

by

Adrian Earl Kibler, Jr.

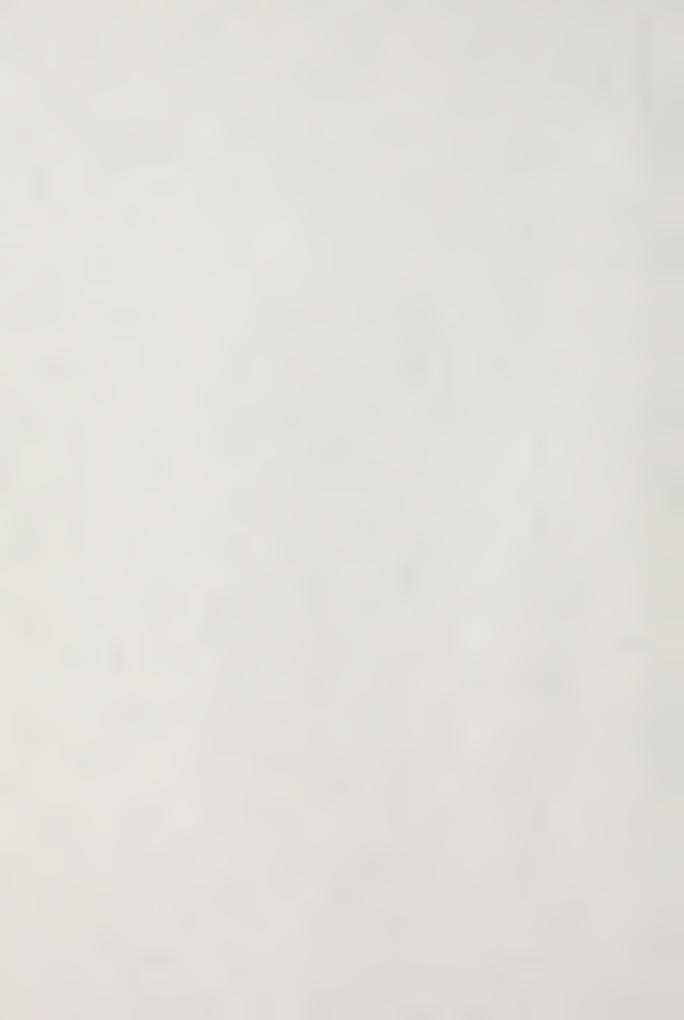
September 1977

Thesis Advisor:

G. Cantin

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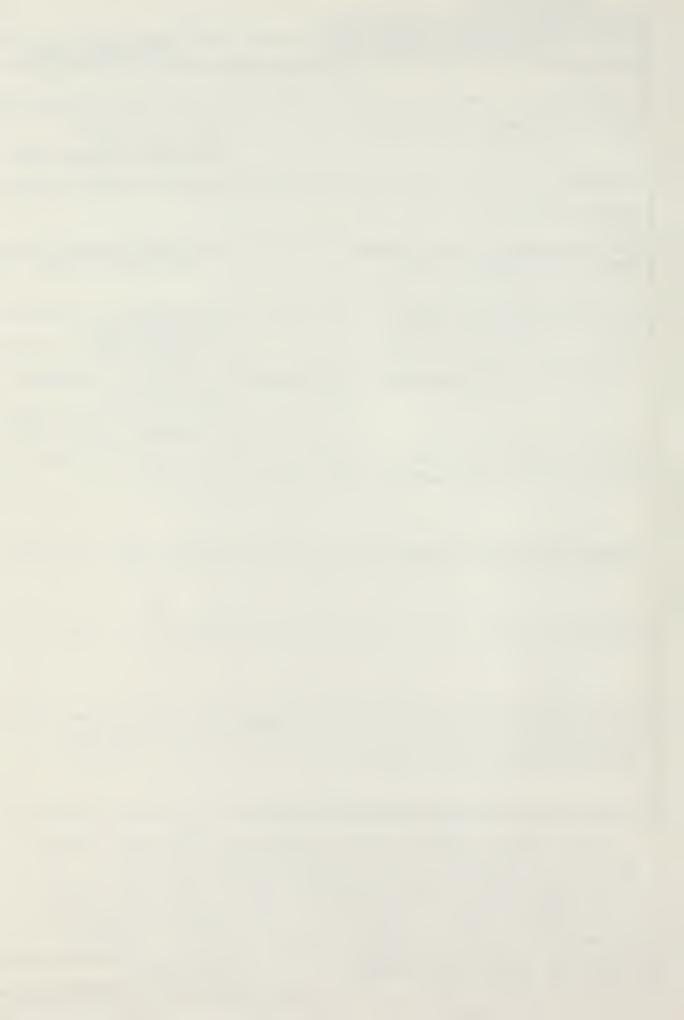
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(20. ABSTRACT Continued)

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by

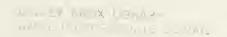
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ABSTRACT

The primary purpose of this thesis was to provide a method of checking the geometry and element connectivity input data for two finite element programs, ADINA and SAP IV. This preprocessor will accept the ADINA or SAP IV data deck, with minor modifications, and generate a graphical display of the finite element model. The display is an oblique orthographic projection, and any orientation may be specified. Several options are available: exploded plots, partial plots, node numbering, element numbering, and others. Elements with three nodes on the same edge are plotted with a continuous curve on each edge generated by an interpolated parabola. Displacement postprocessing capability also exists.

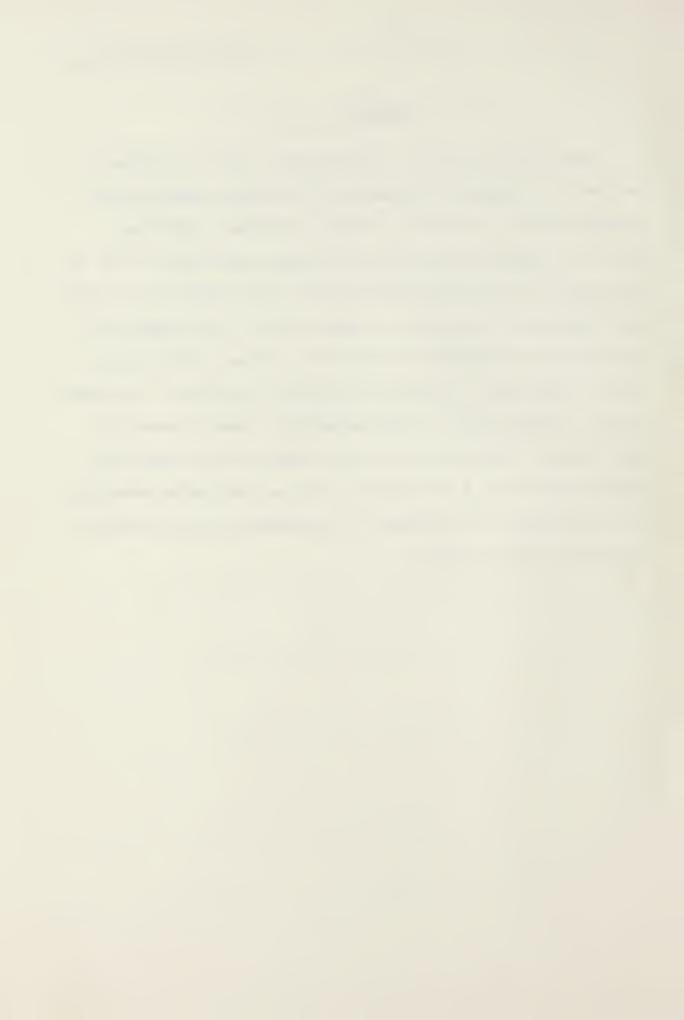
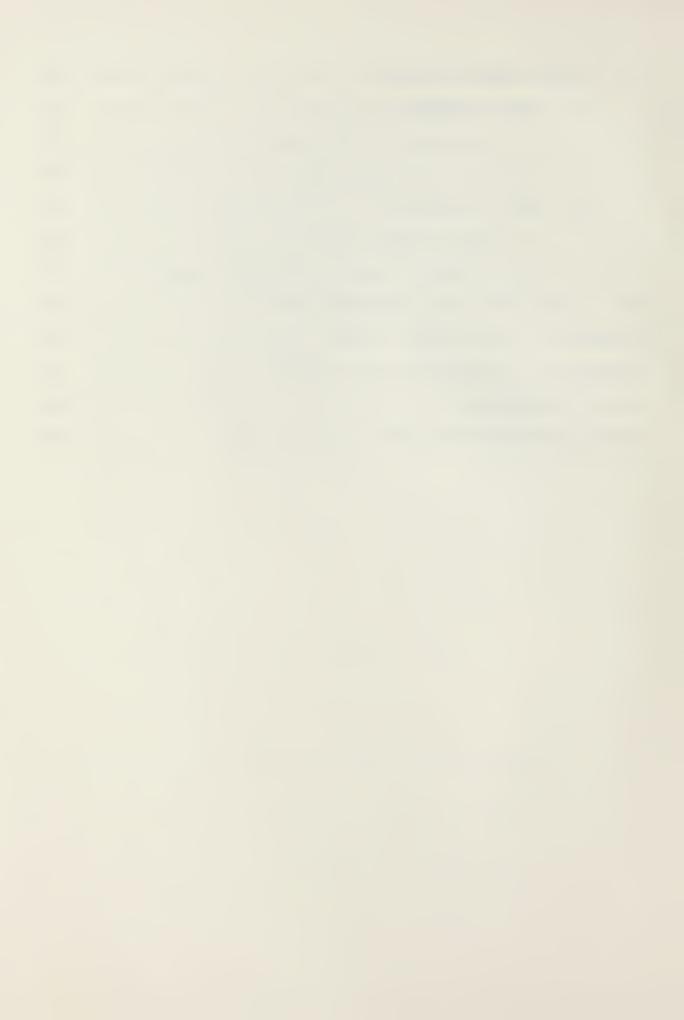


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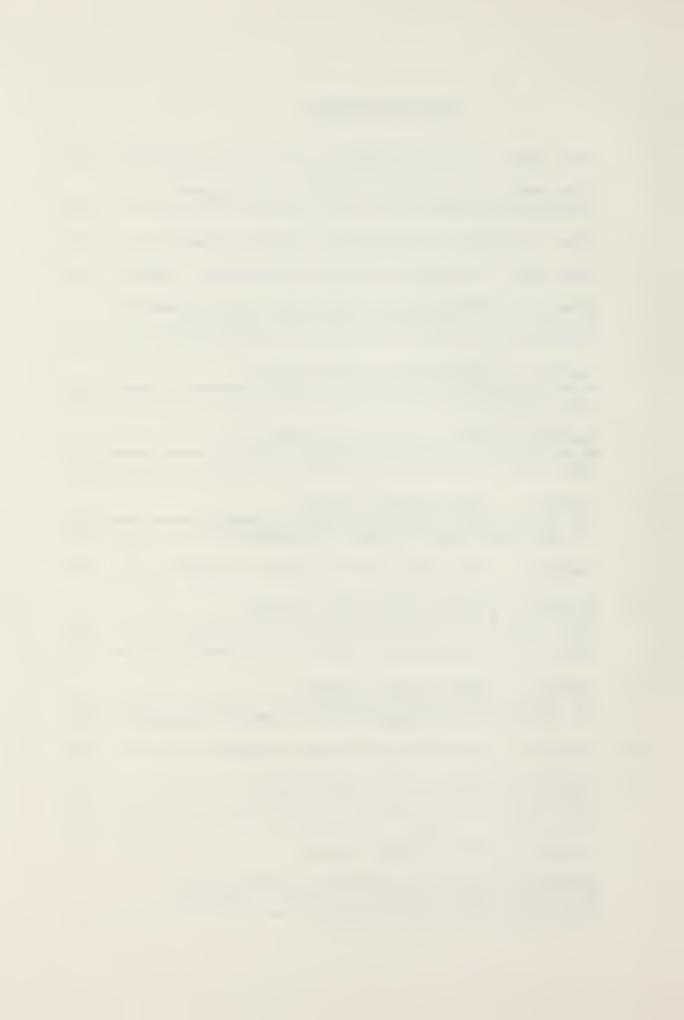


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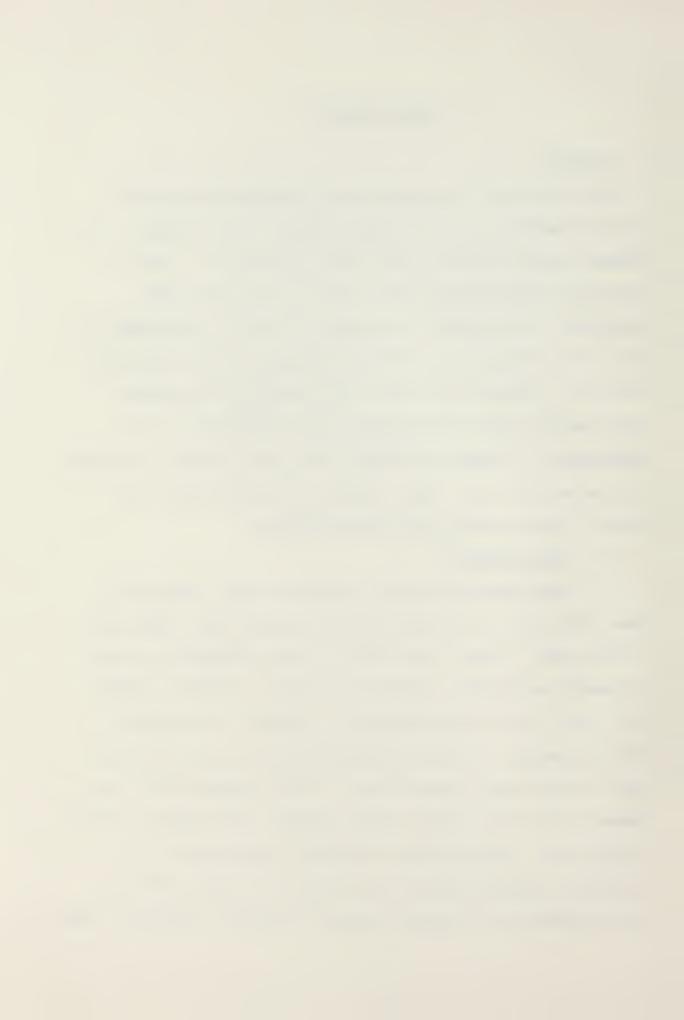
I. INTRODUCTION

A. GENERAL

The continued developments and advancements of the finite element method this last decade have provided greater machine capabilities than ever before. Here at the Naval Postgraduate School (NPS), two of the more favorable finite element programs are SAP IV [reference 1] for linear analysis and ADINA [reference 2] for nonlinear analysis. However, with the large amounts of numerical input/output data and automatic mesh generation, it is impractical to check and reduce this data without a graphical representation. Data checking is divided into two areas: preprocessing and postprocessing.

1. Preprocessing

Preprocessing is the checking of the input data deck. Errors in a finite element program occur basically in two areas. First, how close is the mathematical model (boundary conditions, loading conditions, material properties, etc.) to the real problem? Second, are numerical errors present, or did misinterpretation of instructions occur in data deck preparation? Of the second type, most common errors are found in the geometry and element connectivity data. Preprocessing includes the forming of a graphical representation of the finite element model on which geometry and element errors are easily detected. When



node and element numbering options are available, the graph aids in the physical interpretation of the output data. Preprocessing is not a foolproof method of eliminating errors, but it does provide a tremendous advantage to the user. Preprocessors may be incorporated into the data check mode of the finite element program. However, to modify a large and complex program is dangerous. This may not be the best approach. A safer method is to develop a preprocessor which will read the finite element program deck separately with minimum modifications to that deck.

Postprocessing

Though not as important as preprocessing, postprocessing is extremely helpful in output analysis. Probably the most common and useful type of postprocessing is the contour plot. Appendix C of reference 4 lists a program developed to produce contour plots of stress data from finite element models. Contour plots can easily be adapted to a 2D system, but 3D requires plotting the contours on 2D surfaces, a bit more complicated. Two methods of postprocessing of displacements are the plotting of a deformed model or placing scaled vectors at the nodes. In the cases where the displacements are small, multiplication by a magnification factor produces an exaggerated representation. Like preprocessing, postprocessing can be incorporated into the finite element program directly, or done separately. When done separately, the finite element program must still be modified slightly to obtain a punched deck of the stresses



and displacements in the desired format. This thesis is primarily concerned with preprocessing.

B. HISTORY OF DEVELOPMENT OF PSAP1

A package [reference 4] containing digital computer programs for generating oblique orthographic projections and contour plots was produced by the National Aeronautics and Space Administration's (NASA) Langley Research Center (LRC) and distributed by the National Technical Information Service in January, 1975. The programs are completely general. Both programs contain options for selecting various plotting equipment including CALCOMP, VARIAN, and cathode ray tube (CRT) displays. With minor modifications, they can be adapted to most any system.

1. SUBROUTINE PSAP Implementation

Losh [reference 6], for his master's thesis in aeronautical engineering, implemented the preprocessor and postprocessor program, PSAP, at NPS in December, 1976.

Modifying the LRC package [reference 4], Losh adapted SUBROUTINE PSAP to the NPS IBM 360/67 system using the CALCOMP model 765 plotter. PSAP serves as a preprocessor for SAP IV models, and serves as a postprocessor for displacements of those models. Unfortunately, PSAP is severely limited in the type of elements it can plot.

2. Motivation for SUBROUTINE PSAP1

With the introduction of the ADINA [reference 2] program at NPS in January, 1977, and with expectation of



doing future analysis on ceramic turbine blades, it was desired to expand PSAP to include all ADINA elements and the 8-20 node brick elements in SAP IV. Like PSAP, PSAP1 contains preprocessing and displacement postprocessing capabilities. PSAP1 is presented in this thesis and has the following improvements over PSAP:

- a. Preprocessing for all ADINA elements.
- b. SAP IV 8 and 8-20 node elements.
- c. Expansion of SUBROUTINE ERROR.
- d. Interpolation of curves using shape functions [reference 3] through three points on the edges of the 8-20 node brick elements and the 4-8 node plane elements.
 - e. Improvements in defining the plot origin.
- f. Addition of an option (ISCALE = 0) to plot sections of a model without losing perspective.
- g. Several other minor modifications considered improvements.

C. PRESENT CAPABILITY

PSAP1 has the capability to plot all ADINA elements and all SAP IV elements except the pipe element. It will interpolate curves on the edges of 4-8 node plane elements and 8-20 node brick elements. Many options are given in Appendix A. Some of the more frequently used options are listed below:

- 1. Numbering of grid points (NOTAT = 1).
- 2. Numbering of the elements (NOTAT = 2).
- Exploded plot (KDISP = 2).



- 4. Postprocessing of displacements (NUDISP or NVDISP or NWDISP = 1) in two forms: plot of deformed structure (KDISP = 1) or displacements represented by vectors at the nodes (KDISP = 3; see reference 6).
- 5. Symmetric representation about the XY (KSYMXY = 1), XZ (KSYMXZ = 1) or YZ(KSYMYZ = 1) planes.
- 6. Option to plot sections of the model (partial plot) to obtain a better view. Partial plots may be plotted to the scale of the complete model to avoid losing perspective (ISCALE = 0) or blown up to obtain a better view (ISCALE = 1). Multiple plots may be obtained using the same geometry and same displacement data (KODE = 1), same geometry and new displacement data (KODE = 2), or new geometry and new displacement data (KODE = 3; see figure 1).

In general, multiple plots (sections, partial plots, additional problems) present no problem. Plotting package user courtesy dictates that no more than 5 plots be placed on the CALCOMP plotter at any one time. Also, if the plots contain many elements (especially 8-20 node elements), it is possible to run out of space in the plotting data sets. When this happens, you will receive

ERROR IHC240I STAE, ABEND CODE IS: SYSTEM OB37 SYSPLOT.

The best thing to do is split the run into two jobs. If
the job must be run on one job (i.e., a large number of
elements in the model or an assembly drawing where the
scale of multiple plots is the same), then SYSPLOT space



may be increased [references 7 and 8] by adding the card

//GO.SYSPLOT DD SPACE=(CYL, (needed space)),SYSOUT=C

just prior to card

//GO.FT10F001 DD UNIT = SYSDA

in Appendix A. It would be wise to seek advice from a consultant in Ingersoll 146 if additional plotting space is required.

D. EASE OF MODIFICATION

Both PSAP and PSAP1 are written to maintain as much generality as possible for ease of expansion and modification. Several FORTRAN statements, variables and subroutines are not used. They were left purposely unchanged. Although PSAP1 specifically reads ADINA and SAP IV data, it can easily be expanded to include any geometry and element data format. Simply study the read-in and storage methods (see Section II), and construct appropriate subroutines to read any particular format.



II. PROGRAM ORGANIZATION AND DESCRIPTION OF OPERATION

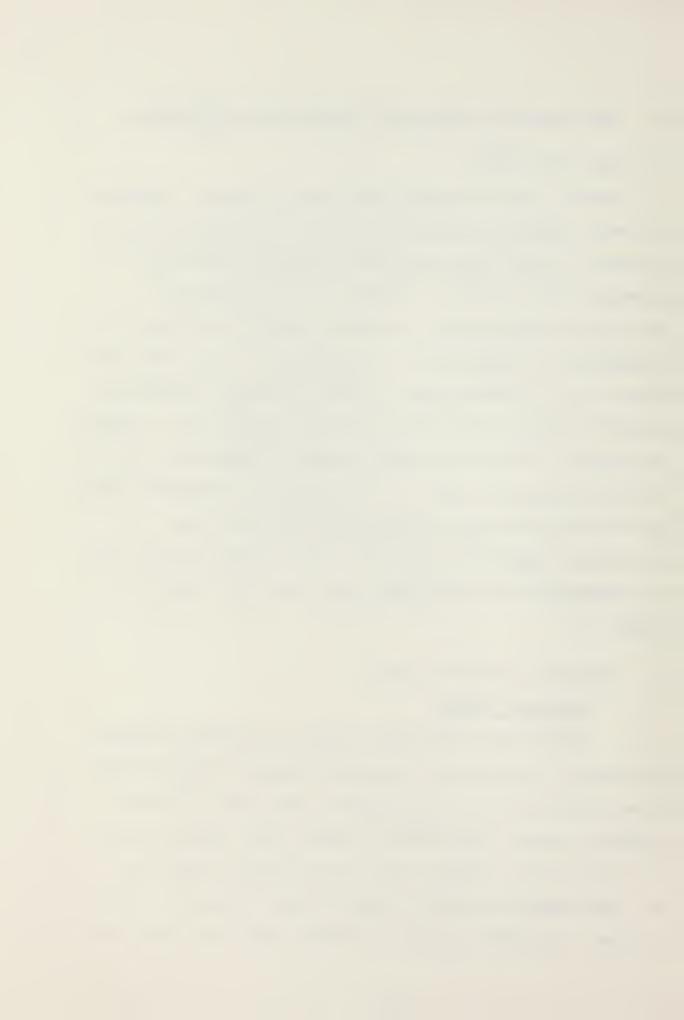
A. PSAP1 FLOW CHART

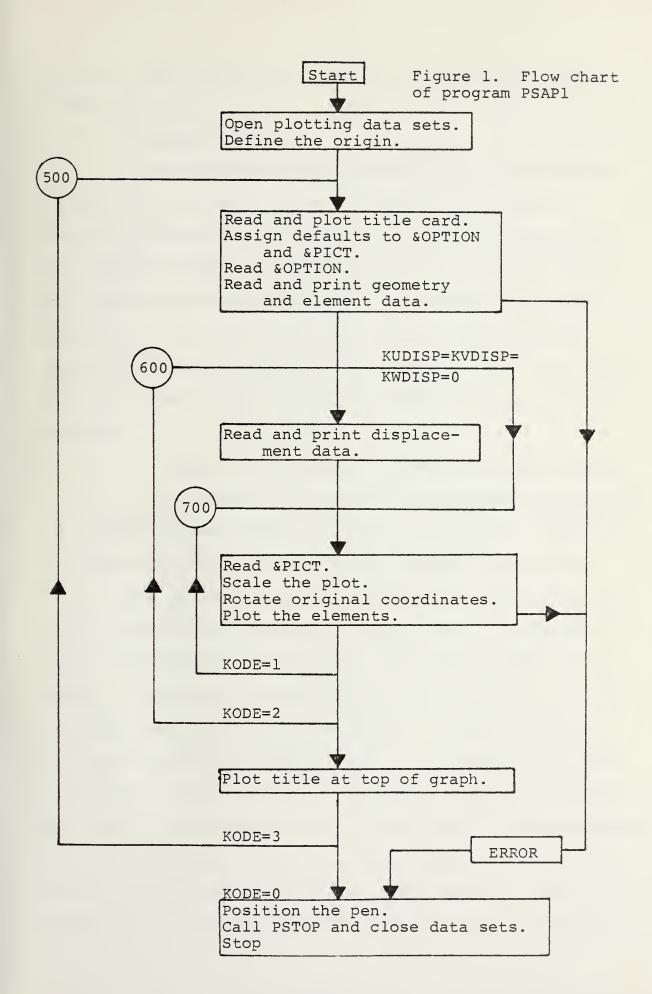
Figure 1 is a condensed flow chart of PSAP1. Probably the most important information given on this chart is the sequence in which the data cards, NAMELIST OPTION and NAMELIST PICT are read. Remember, when generating a sequence of plots, once a parameter has been defined, it retains that value until it is reassigned. Note that when KODE = 1 or 2, the original values of NAMELIST OPTION and NAMELIST PICT are retained until they are changed. However, when KODE = 3 a new title card, NAMELIST OPTION and a set of problem data are read. All variables in NAMELIST OPTION and NAMELIST PICT are assigned their default values. A new problem begins in this case. It is important that the last NAMELIST PICT to be read must contain the value of KODE = 0.

B. NAMELISTS AND EULER ANGLES

1. NAMELIST OPTION

Description and default values of NAMELIST OPTION are given in Appendix A. Basically NAMELIST OPTION variables pertain to the given problem: the number of nodes, geometry format, displacement format, space between plots, and paper size. Default values for NAMELIST OPTION are set, and NAMELIST OPTION is read at the beginning of the problem. Assigned values will remain until exit from the







program (KODE = 0) or a new set of problem data is read
(KODE = 3).

2. NAMELIST PICT

Like NAMELIST OPTION, NAMELIST PICT variable descriptions and default values are given in Appendix A.

Basically NAMELIST PICT variables pertain to a given plot.

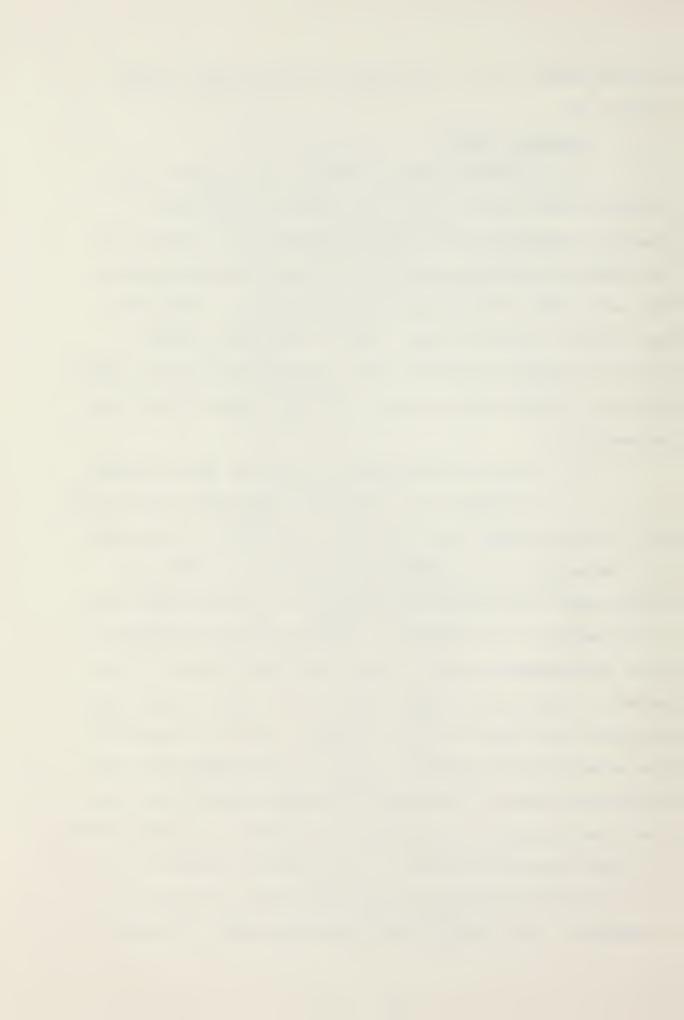
One NAMELIST OPTION may apply to several successive plots,
but each NAMELIST PICT defines a unique plot. That plot

may include the whole model, part of the model and any

options defined in NAMELIST PICT. NAMELIST PICT also specifies the viewing plane through the Euler angles (figure 18,

Appendix A).

a. Oblique Orthographic Projections (Euler Angles) An example of an oblique orthographic projection of a finite element model is given in figure 18 in Appendix A. The model can be viewed in any selected orientation. Euler angle transformations are used to specify orientation of the model to be projected. As described in reference 4, this transformation resolves the coordinate system of the model to a principal viewing plane (i.e., $X_{O}Y_{O}$, $X_{O}Z_{O}$, $Y_{O}Z_{O}$) on which the display is to be plotted. Prior to rotation, the model coordinate system (X,Y,Z) is coincident with the coordinate system containing the viewing planes (X_{O}, Y_{O}, Z_{O}). The viewing planes are fixed, and the model is rotated about its model coordinate system. The rotations (ψ , θ , ϕ) of the body about the model axes (X,Y,Z) are shown in figure 18, Appendix A. The NAMELIST PICT variables KHORZ (horizontal



axis), KVERT (vertical axis), PSI (ψ), THETA (θ), and PHI (ϕ) specify the viewing plane and Euler angles. The order of the Euler angle rotations must be PSI, THETA and then PHI. Mathematical transformations are:

$$[\underline{\underline{A}}_{\psi}] = \begin{bmatrix} \cos \psi & -\sin \psi & 0 \\ \sin \psi & \cos \psi & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[\underline{A}_{\theta}] = \begin{bmatrix} \cos \theta & 0 & \sin \theta \\ 0 & 1 & 0 \\ -\sin \theta & 0 & \cos \theta \end{bmatrix}$$

$$\begin{bmatrix} \underline{A}_{\varphi} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \varphi & -\sin \varphi \\ 0 & \sin \varphi & \cos \varphi \end{bmatrix}$$

SUBROUTINE ROTAT calculates the transformation matrices for every NAMELIST PICT, except if ISCALE = 0. ISCALE = 0 directs the scale of the plot to be the same as that of the



previous plot. Should a rotation occur with ISCALE = 0, the plot width could exceed the paper width.

b. Scaling

The safest scaling method is automatic scaling (ISCALE = 1). The user may specify a scale (ISCALE = 2) and the plot origin (XORGN,YORGN), but one must be careful not to run the plotting pen off the graph paper. ISCALE = 0 is a very useful option. The plot will use the same scale as the previous plot. It is useful in an assembly graph where examination of a mesh in sections without losing perspective is desired. Example 3, Section III, illustrates the option ISCALE = 0. When ISCALE = 1 in a NAMELIST PICT defining a partial plot, a "blow-up" of that section is obtained. ISCALE cannot be zero in the first NAMELIST PICT.

c. Partial Plots

To develop a partial plot, three methods of segregating elements exist: first, by the X, Y, and Z cutting planes; second, by node numbers, and, third, by element numbers. If a model has an area where the elements are relatively small, a "blow-up" may be desired. Choose a numbering scheme or coordinates to define the section to be segregated using one of the methods above. Example 3 (figure 14, Section III) uses X, Y, and Z cutting planes to define the partial plots. Example 4 (figure 17, Section III) uses element numbers to section the plots.



C. NODAL POINT (GEOMETRY) INFORMATION READ-IN

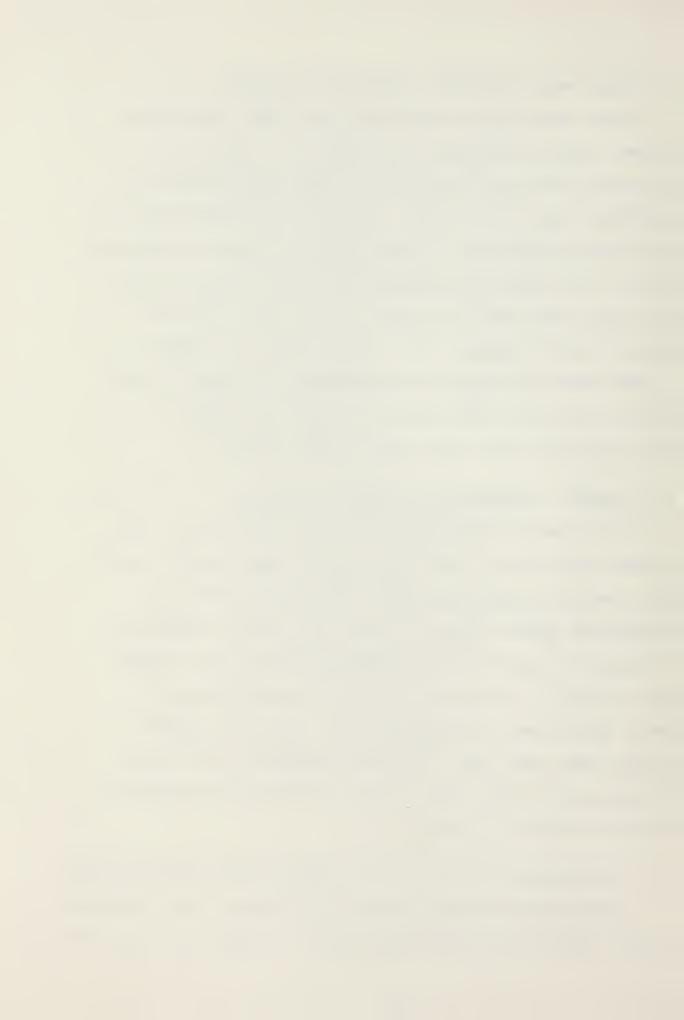
Nodal point data is read in by the GEOMn subroutines (GEOM1, GEOM2, and GEOM9, see figure 2). Since SAP IV and ADINA data decks are similar, SUBROUTINES GEOM1 and GEOM9 are also very similar. They are both constructed to read and generate data in exactly the same way as ADINA and SAP IV. All data not needed by PSAP1 is disregarded and the nodal point data is stored in array ZZZ (figure 3). After studying storage array ZZZ and GEOM1 (or GEOM9), a user moderately familiar with FORTRAN programming could easily construct a user supplied subroutine (GEOM2) to read the nodal point data in any desired format.

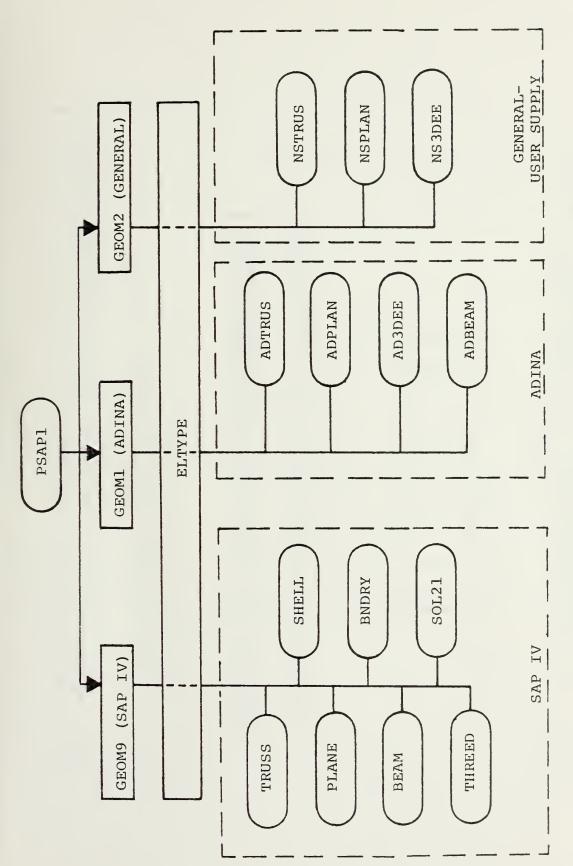
D. ELEMENT (CONNECTIVITY) INFORMATION READ-IN

After reading and storing the nodal point data, the element data must be read. The GEOMn subroutine will read the element control card (NPAR, references 1 and 2).

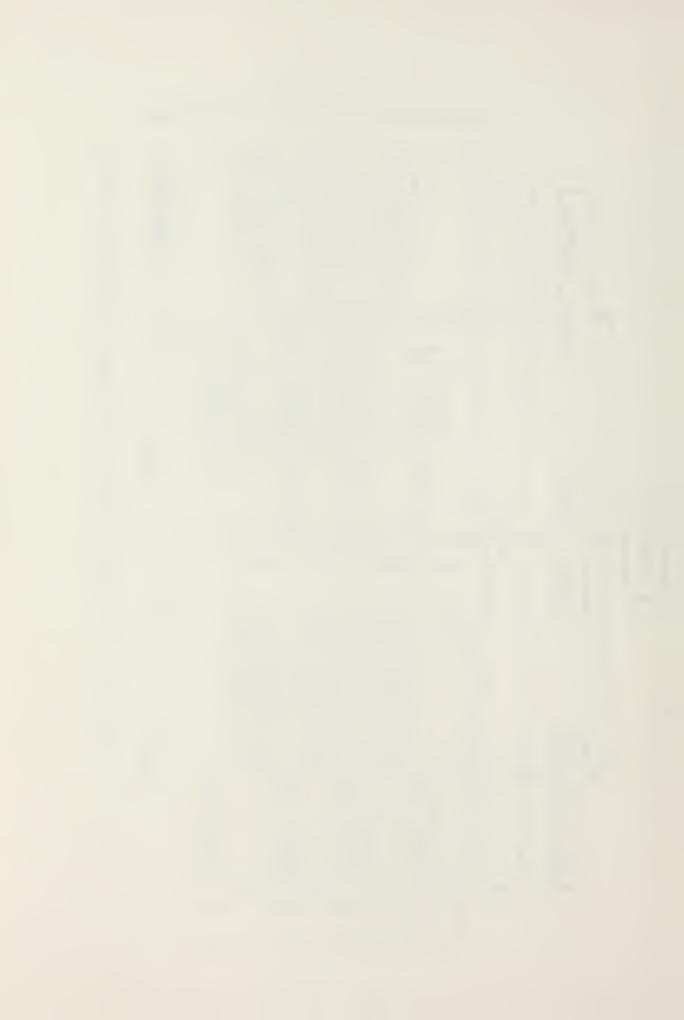
SUBROUTINE ELTYPE (figure 2) calls the proper element subroutine to read the element data specified on the element control card. If several groups of elements are to be read, the process is repeated until all of the element groups have been read. Although the nodal point data is stored in array ZZZ, the element connectivity is read and stored on device 10 (disk).

E. DISPLACEMENT DATA READ-IN FOR DISPLACEMENT POSTPROCESSING Displacement data may be read in (figure 1) by SUBROUTINE DATA9 (KDATA = 9) or SUBROUTINES DATA1 or DATA5 (user supplied,





Flow chart for reading geometry and element connectivity data. Figure 2.

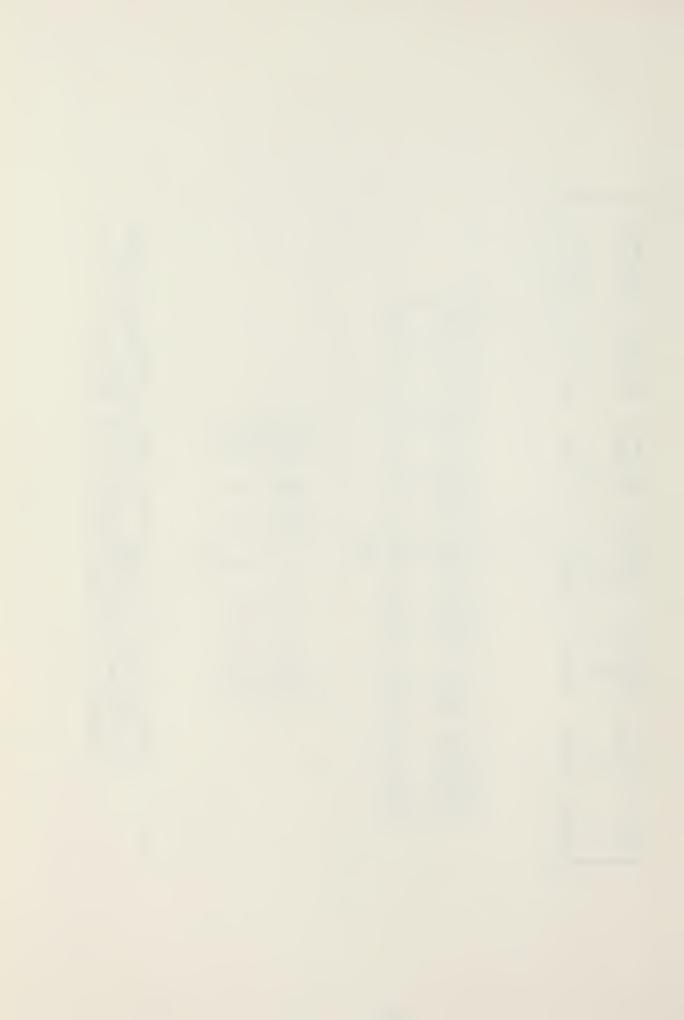


```
ZZZ(1) ZZZ(N+1) ZZZ(2N+1) ZZZ(3N+1) ZZZ(4N+1) ZZZ(5N+1) ZZZ(6N+1) ZZZ(6N+1) ZZZ(6N+2) ZZZ(2) ZZZ(N+2) ZZZ(3N+2) ZZZ(4N+2) ZZZ(5N+2) ZZZ(6N+2) "
                                                                                               ZZZ (7N)
                                                                                               (N9) ZZZ
                                                                                               ZZZ (5N)
                                                                                                                                              (a)
                                                                                               ZZZ (4N)
                                                                                               ZZZ (3N)
                                                                                               ZZZ (N) ZZZ (2N)
```

NUMPT(N) XPT(N) YPT(N) ZPT(N) UPT(N) VPT(N) WPT(N) NUMPT(1) XPT(1) YPT(1) ZPT(1) UPT(1) VPT(1) WPT(1) NUMPT(2) XPT(2) YPT(2) ZPT(2) UPT(2) VPT(2) WPT(2) " (p)

	Wl	W2	=	=	MN	
	Vl	V2	=	=	NN	
	Ul	U2	=	=	ND	
	z_1	22	=	=	ZN	(2)
	X1	Y2	=	=	ΧN	
	Xl	X2	=	=	XN	
L	Н	7	=	=	Z	l

N = The number of nodes. (a) Array in subroutine PSAP1. (b) Arrays in subroutines called by PSAP1. (c) Nodal coordinates and displacements in (a) and (b). Nodal point and displacement storage arrays. Figure 3.



KDATA = 1 or 5). When read, displacement data is stored in the last three columns of array ZZZ (figure 3). PSAP1 can postprocess displacements for both ADINA and SAP IV. The difficulty comes in obtaining a punched deck of cards. Reference 6 gives a description of how to obtain a deck of cards for SAP IV in a format acceptable to SUBROUTINE DATA9. ADINA has no such provision. However, when preprocessing, the displacement data will be omitted (NUDISP=NVDISP=NWDISP=0), and this step will be by-passed.

F. PLOTTING LOGIC

SUBROUTINE PLOTX (figure 4) is the main plotting routine. Since the nodal point data is stored in array ZZZ and the connectivity is stored on device 10, it is a simple matter to read the connectivity from device 10 (one element at a time), and connect the nodes as they are defined in references 1 and 2. For example, NEND = number of nodes defining the connectivity of a single element, NUMEL = the element number and NODE(NEND) is the array containing the connectivity.

Device 10 contains this information successively for each element. The statement

READ(10) NEND, NUMEL, (NODE(I), I=1, NEND)

will read the element connectivity to be plotted. The 8-20 node brick (ADINA and SAP IV) and the 4-8 node plane elements (ADINA) may have 3 points defining each edge. If the midpoint node is defined, then isoparameteric



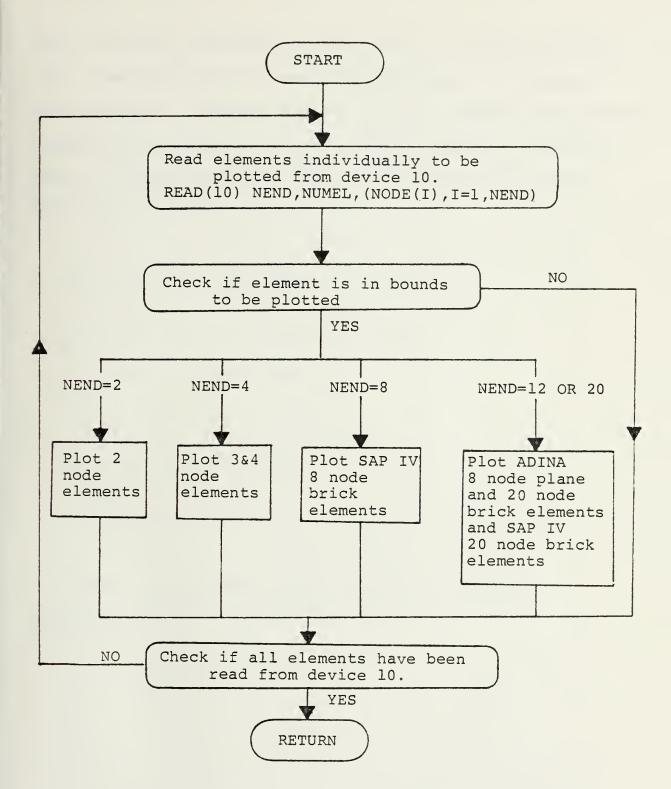


Figure 4. Flow chart for PSAP1 plotting subroutine, PLOTX. Array NODE contains the connectivity of the element being plotted. NEND = the number of nodes defining the connectivity of a single element. NUMEL = the element number.



shape functions (reference 3) are used to interpolate along the three-node edges. These shape functions are identical to those used by ADINA and SAP IV, so the geometry represented graphically is identical to the problem solved in ADINA and SAP IV. SUBROUTINE CURVE does the interpolation with the following equations:

$$X_{0} = N1 * X_{01} + N2 * X_{02} + N3 * X_{03}$$
 $Y_{0} = N1 * Y_{01} + N2 * Y_{02} + N3 * Y_{03}$
 $N1 = S * (S - 1.0) / 2.0$
 $N2 = - (S + 1.0) * (S - 1.0)$
 $N3 = S * (S + 1.0) / 2.0$
 $-1.0 \le S \le 1.0$

PSAP1 uses the NPS plotting package [reference 5] subroutines.



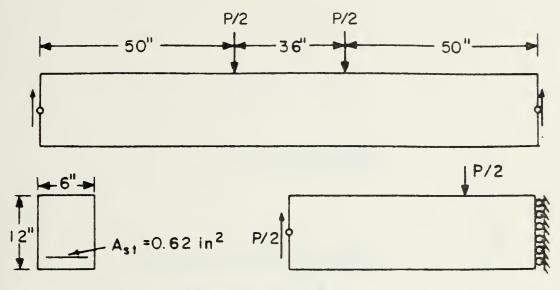
III. PSAP1 SAMPLE PROBLEMS

The following examples have been chosen to illustrate some of the most useful options of PSAP1. Prior to attempting to use PSAP1, the user should have the problem defined and the cards punched in the format of references 1 and 2. Appendix A of this thesis gives a complete description of deck preparation for PSAP1 here at NPS. This section should prove helpful in the understanding and interpretation of the options presented in Appendix A.

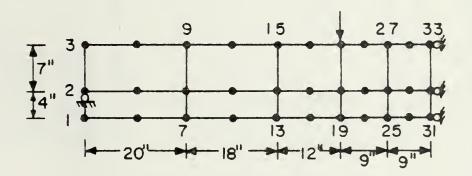
A. ADINA EXAMPLES

This example was chosen because it illustrates
the importance of the exploded plot when more than one
element group is used. It is taken from the ADINA manual
[reference 1]. Figure 6 is a listing of the data cards
as they are prepared for ADINA. Figure 7 indicates how
that deck would be modified for PSAP1. Note: load cards
are removed, NAMELIST OPTION and NAMELIST PICT are added,
and the title to be plotted on the graph is added in figure
7. Otherwise, figures 6 and 7 are the same. Figure 8,
part (a), illustrates an undistorted (KDISP = 0) PSAP1 plot
with the nodes numbered (NOTAT = 1). Figure 8, part (b),
shows the same mesh in an exploded form (KDISP = 2) with
the elements numbered (NOTAT = 2). Note how the truss
elements are visible in the exploded plot.





BEAM DIMENSIONS



FINITE ELEMENT IDEALIZATION

MATERIAL PROPERTIES:

$$\sigma_{\rm c}$$
 = 3740 psi
 $\sigma_{\rm 1}$ = 458 psi
 $\sigma_{\rm y\,steel}$ = 44000 psi
 $E_{\rm 0\,concrete}$ = 6100 ksi
 ν = 0.2
 $E_{\rm steel}$ = 30000 ksi

E tate = 300 ksi

Figure 5. Example 1, ADINA truss and 8 node plane elements, Reinforced Concrete Beam (Given on page 84, reference 2).

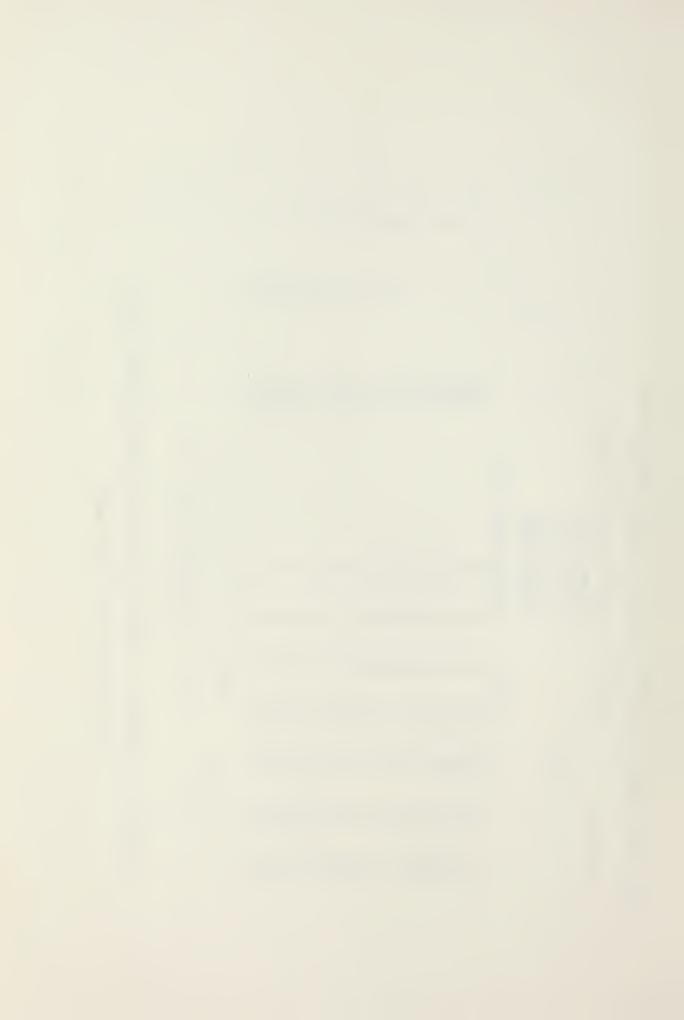


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2. Example 1, ADINA input deck listing, page 1 of Figure 6.

***** Not part of input deck.



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Example 1, ADINA input deck listing, page 2 of 2. Figure 6.

***** Not part of input deck.



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***** Not part of input deck. Figure 7. Example 1, PSAP1 input deck listing, page 1 of 2.



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2 2 of Example 1, PSAP1 input deck listing, page Figure 7.

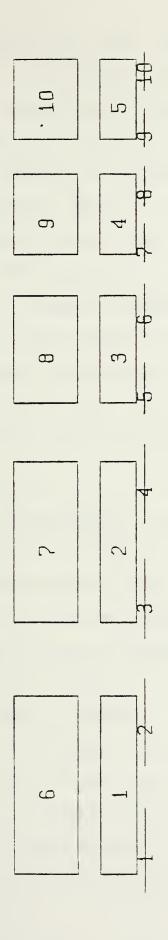


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12	11	10
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(a) Undeformed structure (KDISP=0), nodes numbered (NOTAT=1).

Example 1, PSAP1 output graphs, page 1 of 2. Figure 8.





(b) Exploded plot (KDISP=2), elements numbered (NOTAT=2).

Figure 8. Continued, page 2 of 2.



2. Flat Plate With Hole (example 2, figure 9)

This is a well known problem with which one can calculate the stress concentration on a hole in a plate under axial tension. Figure 10 is a listing of the PSAP1 deck set-up. The mesh is composed of ADINA variable 4-8 node plane elements. Notice on figure 11, parts (a) and (b), how the interpolating shape functions round off the 3-node edges. Part (a) has the nodes numbered (NOTAT = 1). Part (b) has the elements numbered (NOTAT = 2), and illustrates the use of the symmetry option (KSYMXY=KSYMXZ=1). The symmetry option enables one to obtain a picture of the complete plate even though the model only consisted of a quarter plate with proper boundary conditions.

B. SAP IV EXAMPLES

1. SAP IV Truss Problem (example 3, figure 12)

Figure 13 is a listing of the PSAP1 data deck.

Figure 14 indicates how multiple partial plots can be used to obtain a better representation of the model. Part (a) of figure 14 is the complete model. Part (b) is the left half (XXMAX = 50'), and part (c) is the right half (XXMIN = 50', XXMAX = 1.0E20'). Notice also that for Parts (b) and (c), ISCALE = 0, which means succeeding plots have the same scale as the first. Had ISCALE equaled 1 (blow-up), then the width of the half view would have been the same as the complete model. Figure 14 size is limited by the NAMELIST PICT variable PLOTSZ.

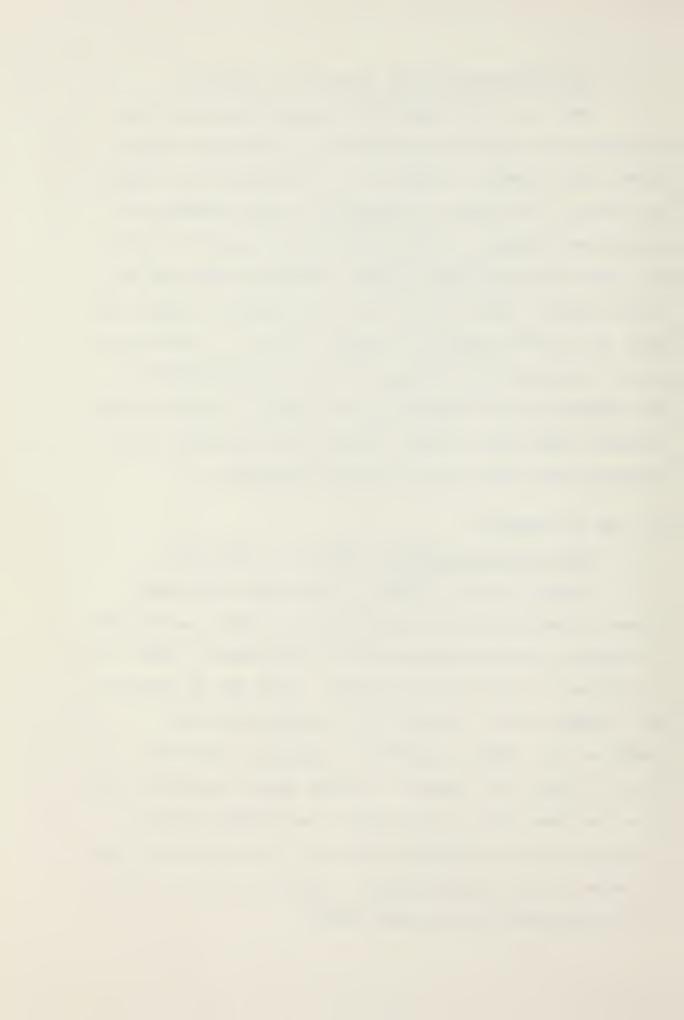


Figure 9. Example 2, flat plate with a hole in tension. ADINA 4-8 node plane element.

Thickness = 1 inch

Young's modulus = 30.0 X 10⁶ psi

Poisson's ratio = .333

Total elements = 18

Total nodes = 44

Distributed Load =



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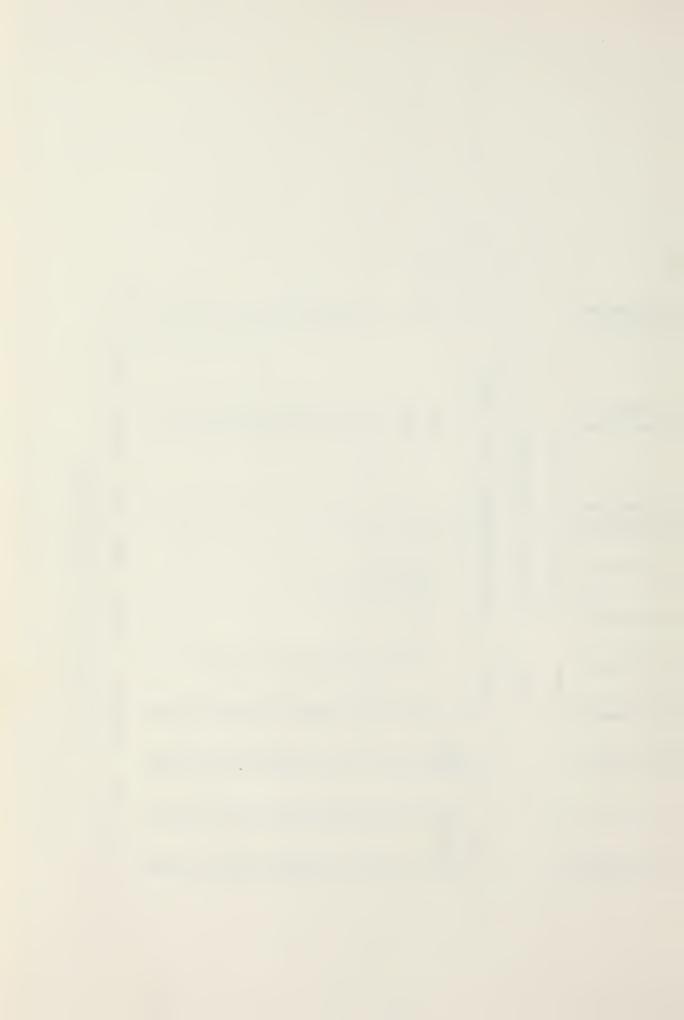
Figure 10. Example 2, PSAP1 input deck listing, page 1 of 3.



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Example 2, PSAP1 input deck listing, page 2 of 3. Figure 10.



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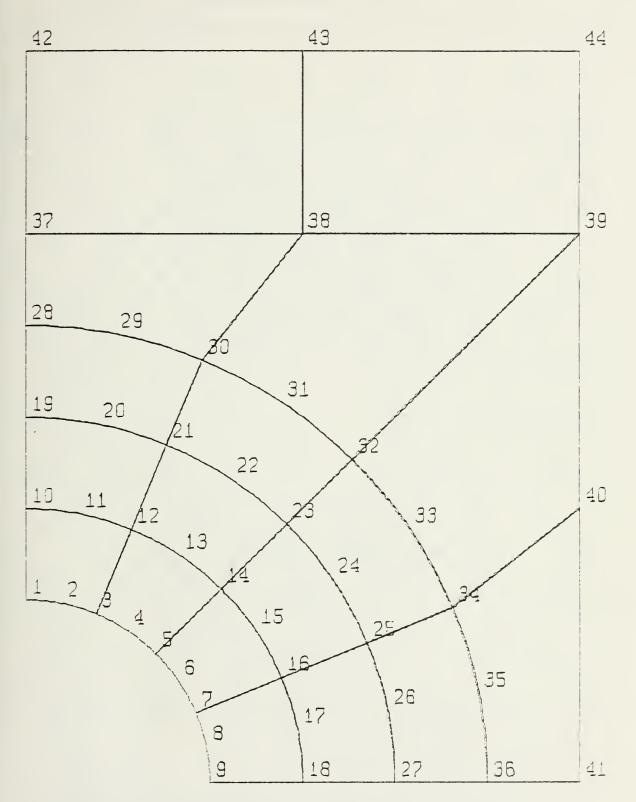
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3. of Example 2, PSAPl input deck listing, page Figure 10.



Figure 11. Example 2, PSAP1 output graphs, page 1 of 2.



(a) Actual mesh, nodes numbered.

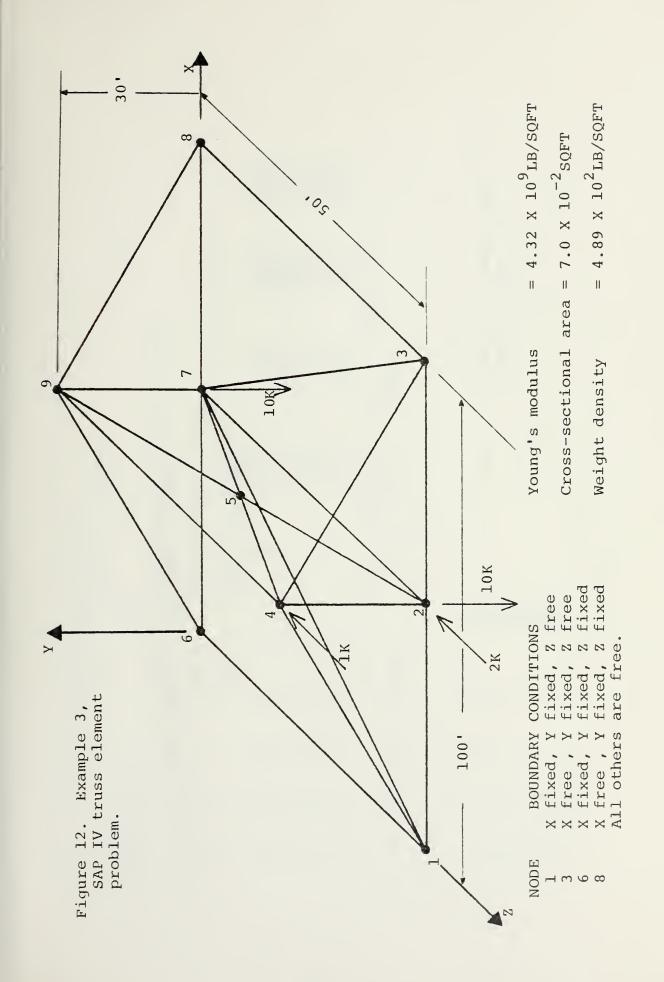


Figure 11. Continued, page 2 of 2.

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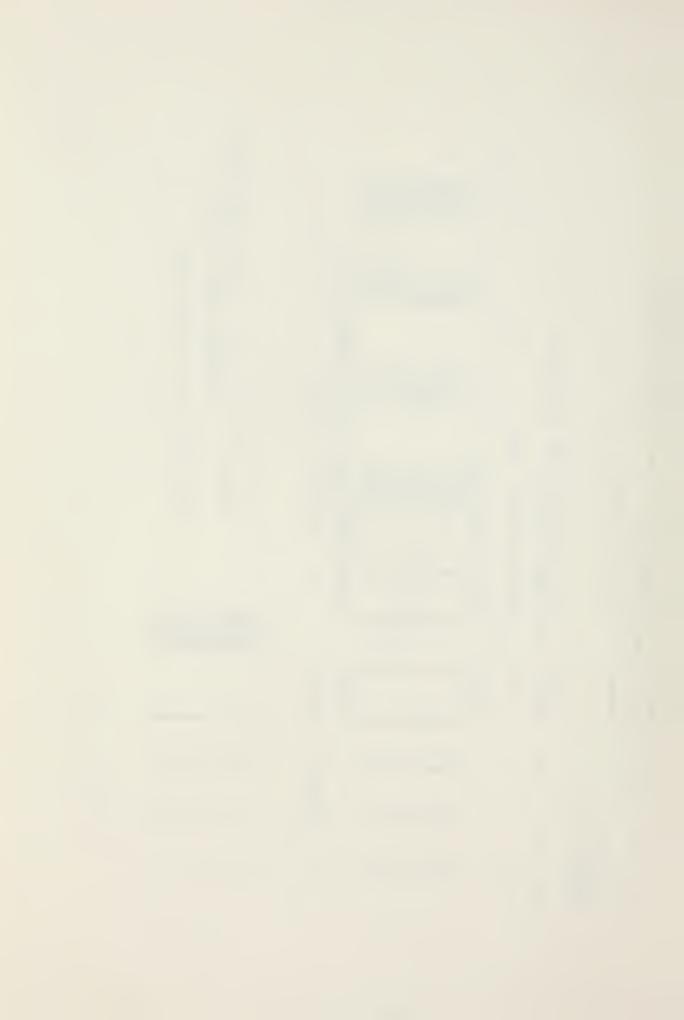
(b) Symmetric representation, elements numbered.







deck Example 3, PSAP1 input of deck page 1 CATA GRAPH input EMENT listing, IV EXAMPLE Z of TRUSS EL PLOTTED 4.89E02 part 13. TITLE CARD FOR SAP WITH INNER ELEMENTS Not CCNTRUL CARD 8E DIMENSIONAL PCINT DATA 100.0 100.0 50.0 50.0 100.0 Figure 7.0E-02 NAMELIST CPTION 10 **** ***** PSAP1 TITLE TRUSS EXAMPLE PROBLEM MASTER E 0 NODAL THRI 0 ***** PROBLEM *** *** *** 6.5E-J6 0 000000000 <u>\</u> TRUSS 4.32E09 22444077 SAP 0-00-00 EOFTICA YSPACE=C.25, EENC PSAF SAMPLE 20 00000000 **もとしてらとしと** A E KIBLER S **しこう 4 らら り** 12214501000



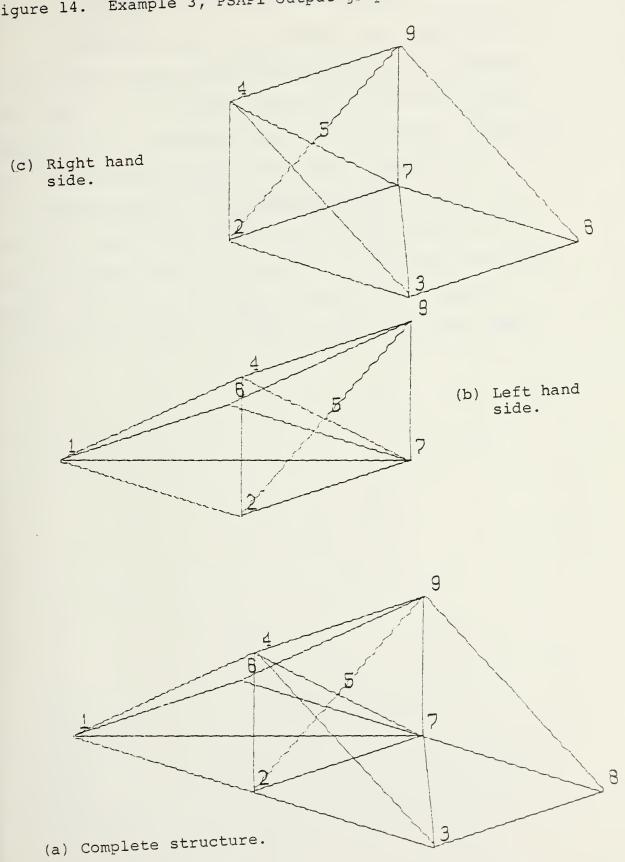
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Example 3, PSAP1 input deck listing, page 2 of 2. Figure 13.



Figure 14. Example 3, PSAP1 output graphs.





. 2. Cylindrical Bar With Spherical Hole (example 4, figure 15)

This mesh could have several uses. Two might be to calculate stress concentrations if the bar is under axial load or to calculate loading if the void is under pressure (i.e., dispersed nuclear fuel pellet). Figure 16 is a listing of the PSAP1 data deck. Figure 17, part (a), is a representation of the complete model. Parts (b), (c), (d), and (e) of figure 17 are partial plots of the total structure using options of the undeformed structure (KDISP = 0) with node numbering (NOTAT = 1), and the exploded plot (KDISP = 2) with element numbering (NOTAT = 2).



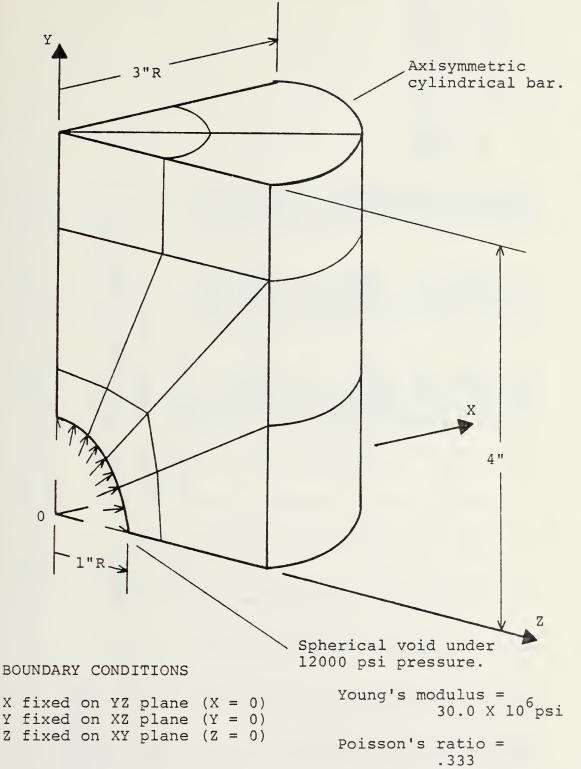


Figure 15. Example 4, six inch diameter cylindrical bar with a two inch diameter spherical void on the center line under pressure.



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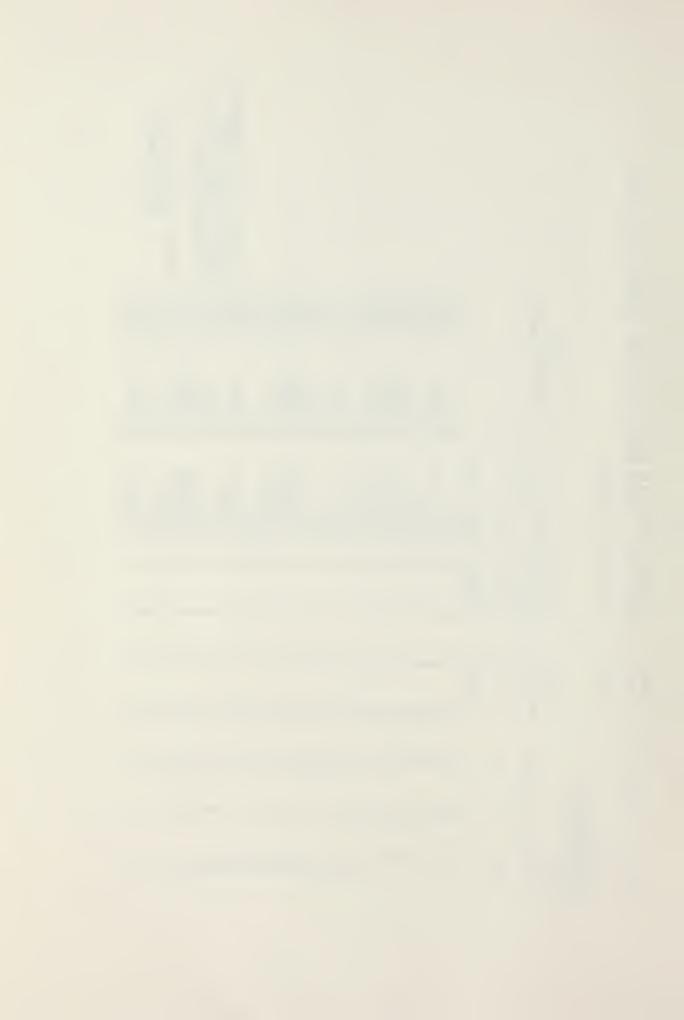


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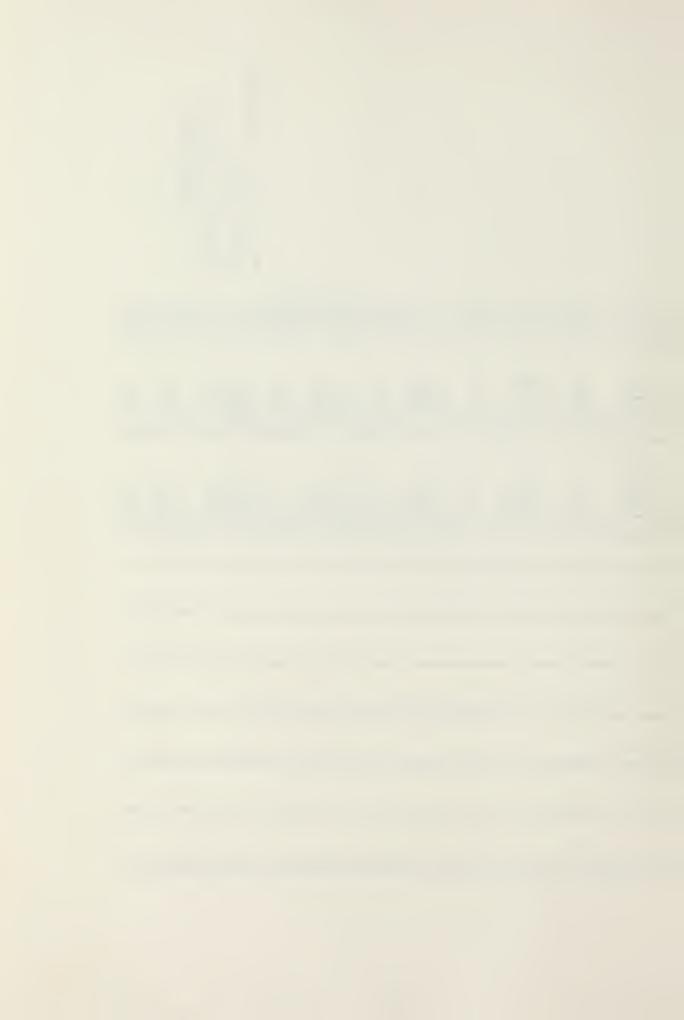


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16 of Not part of input deck



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***** Not part of input deck. 9 Figure 16. Continued, page 4 of



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***** Not part of input deck. Figure 16. Continued, page 5 of 6.



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KVERT=3,						
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THETA=10.0,						
PSI=45.0.						
ISCALE=2,						
XCRCN=C.4.						
PSCALE=0.5714,						
KOCE=1,						
ω L						

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Figure 17. Example 4, PSAP1 output graphs, page 1 of 5.

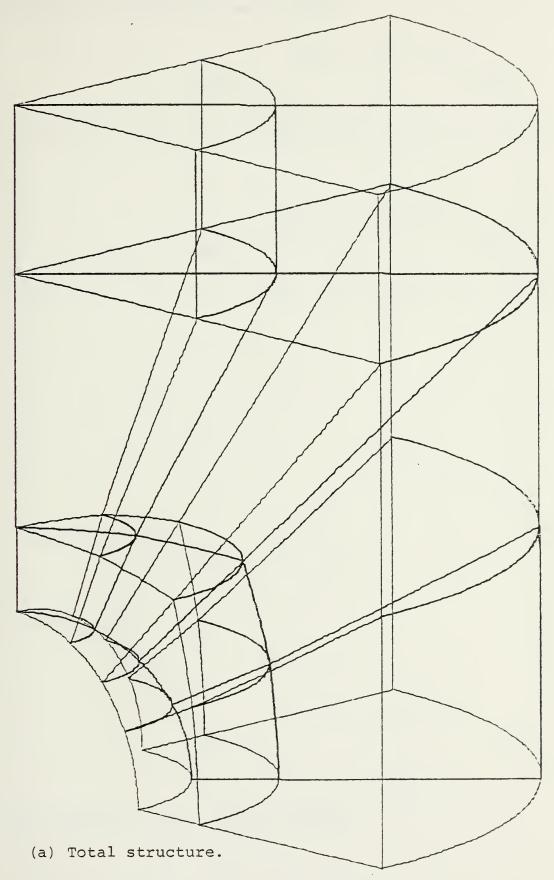
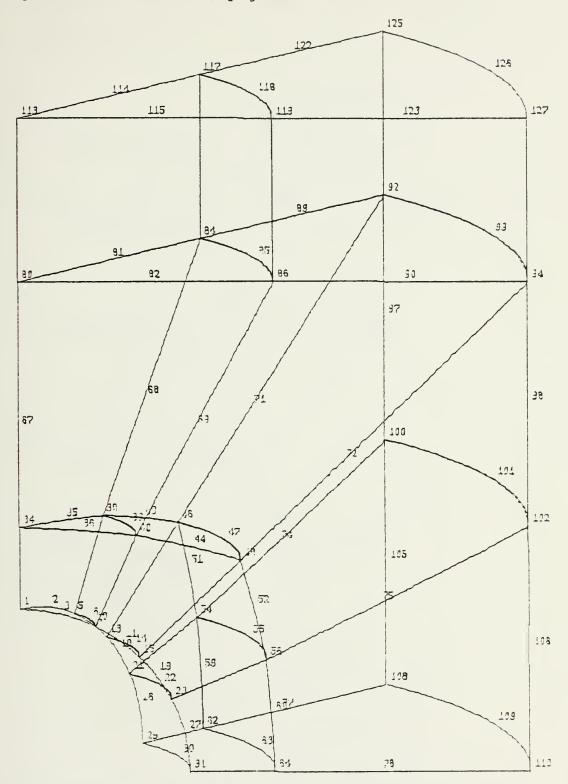




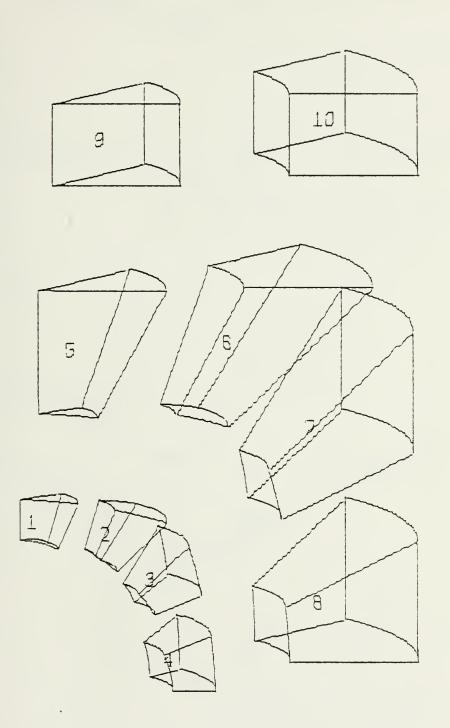
Figure 17. Continued, page 2 of 5.



(b) Elements 1-10, nodes numbered.



Figure 17. Continued, page 3 of 5.



(c) Elements 1-10, elements numbered, exploded plot.

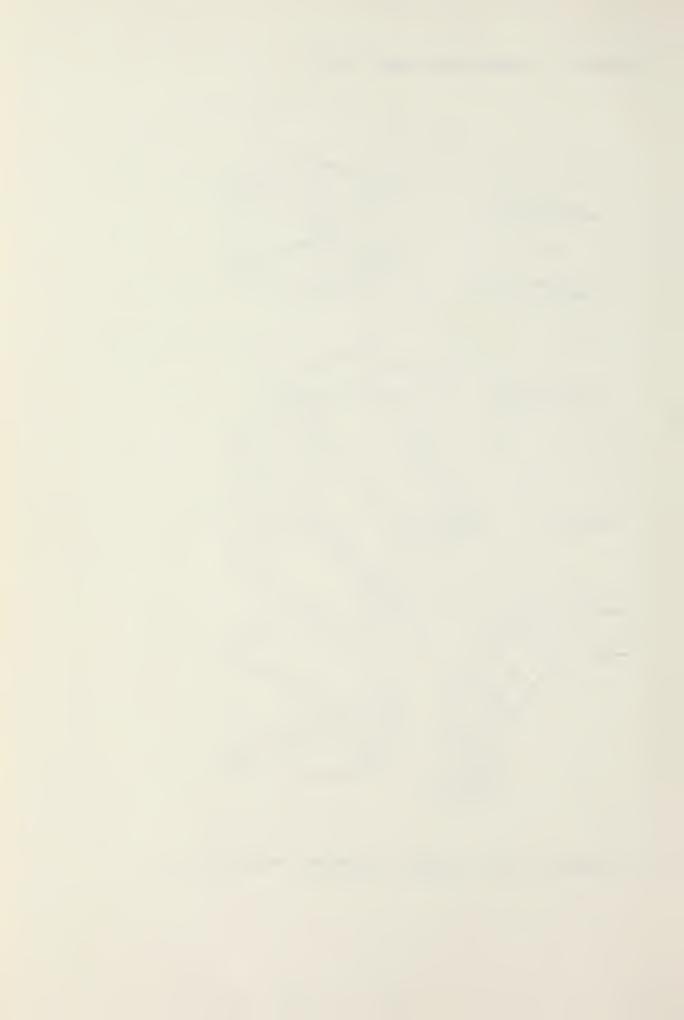
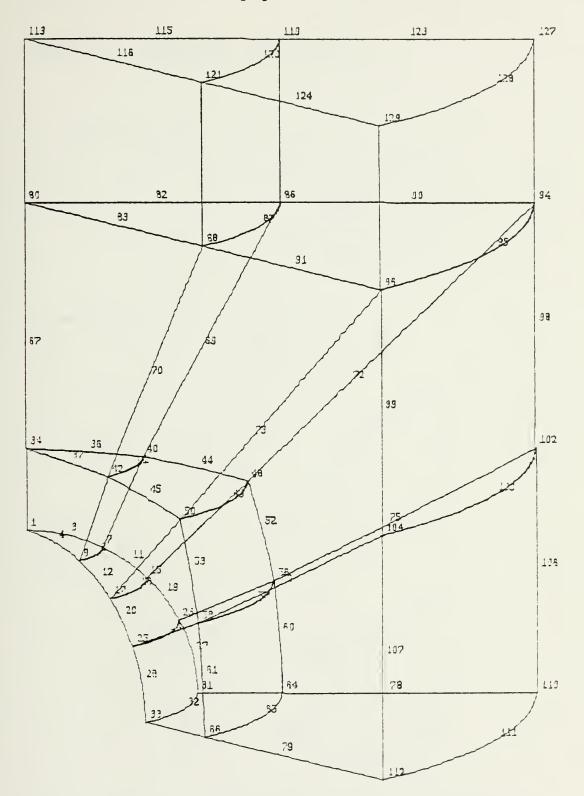


Figure 17. Continued, page 4 of 5.



(d) Elements 11-20, nodes numbered.

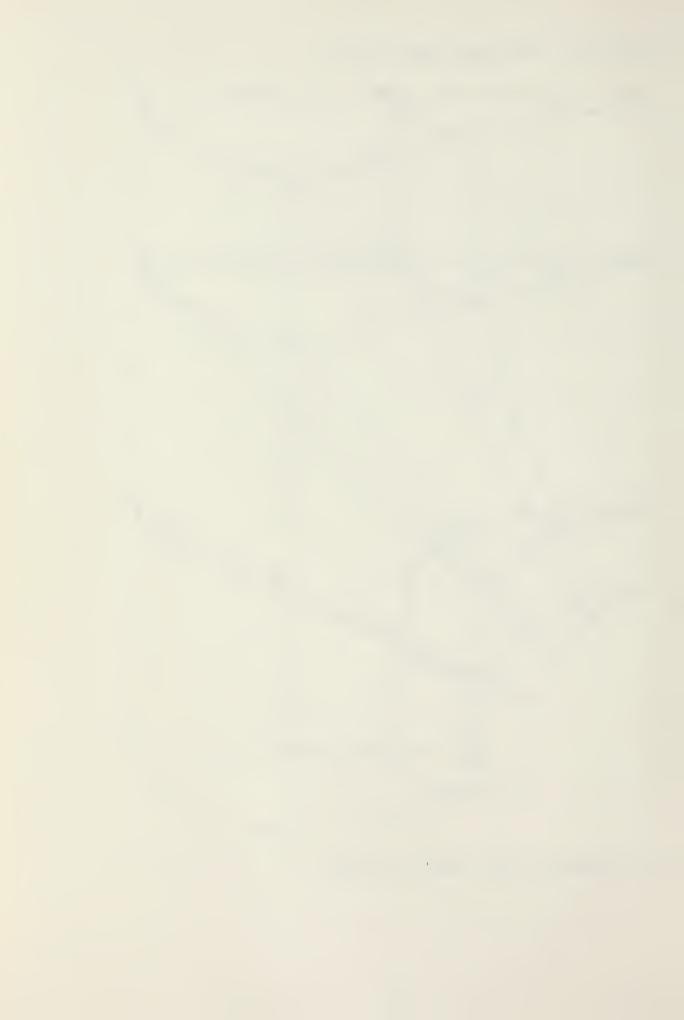
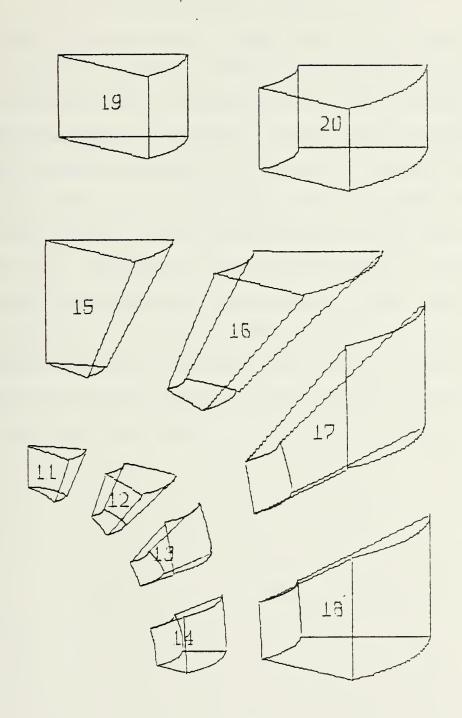


Figure 17. Continued, page 5 of 5.

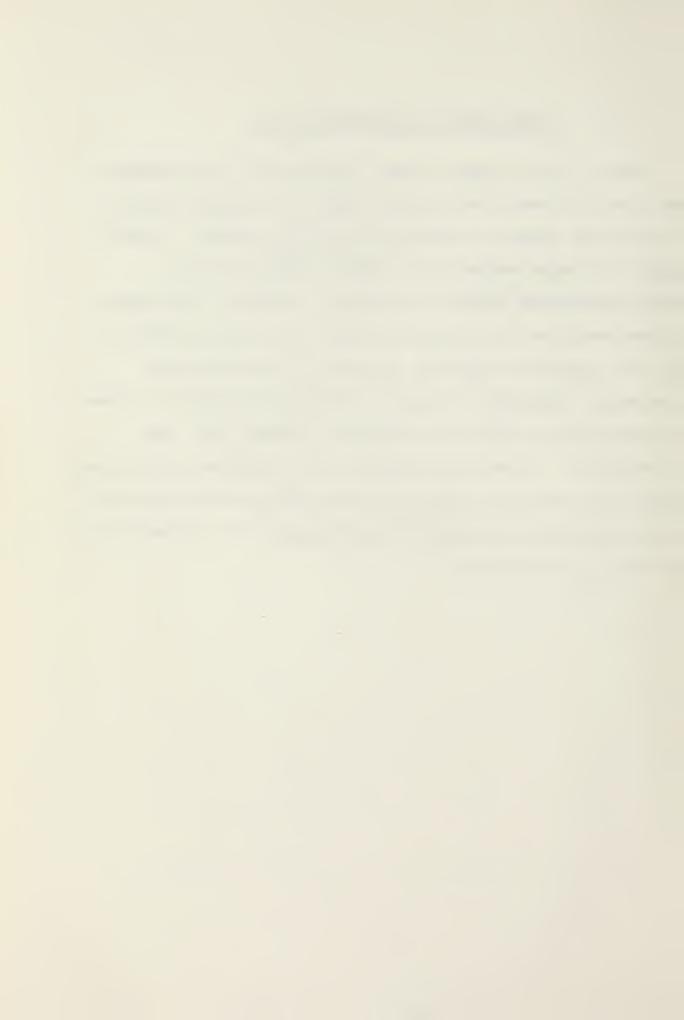


(e) Elements 11-20, elements numbered, exploded plot.



IV. CONCLUSIONS AND RECOMMENDATIONS

With a little study of PSAP1 and figure 2, one realizes how simple it would be to expand PSAP1 to include virtually an unlimited number of geometry data input formats. Simply supply the GEOMn subroutines, element subroutines and modify SUBROUTINE ELTYPE if necessary. Another interesting project would be to incorporate PSAP1 into ADINA and SAP IV so that a mesh plot could be obtained in the data check mode only. Reference 4 contains routines for plotting stress contours which could be incorporated. Hidden line logic is available. It would be difficult but could be incorporated. Hidden line plots are pretty, but they are not very practical when preprocessing because in preprocessing it is advantageous to see all of the nodes.



APPENDIX A

PSAP1 USERS MANUAL

I. NAMELISTS

It may be useful for the user to review NAMELISTs in any good FORTRAN manual. However, a short description of the NAMELIST input is given here. Only columns 2 through 80 of each card will be read. The computer expects to find a special delimiter symbol in column 2 of the first card followed by the NAMELIST name. The delimiter symbol for the IBM 360-370 series is the ampersand & ; other processors use the dollar sign \$. Following the first card comes the list of variables and their assigned values. Some important points about the variables are:

- A. Variables and their values need not appear in any special order.
- B. Predefined variables need not appear in the list if it is not necessary to change the value.
 - C. A comma should follow each assigned value.
- D. It is recommended that each variable appear on a separate card to facilitate change.

The last card following the NAMELIST variables contains, beginning in column 2, the delimiter sign followed by the word END. For example, &OPTION (read NAMELIST OPTION) contains 12 variables. All are initially assigned default



values. But, suppose three of those values (NNDEST=200, KGEOM=9, YSPACE=2.0) do not apply to a specific problem. The &OPTION would be read as follows:

_&OPTION _NNDEST=300, _KGEOM=1, _YSPACE=5.0, _&END

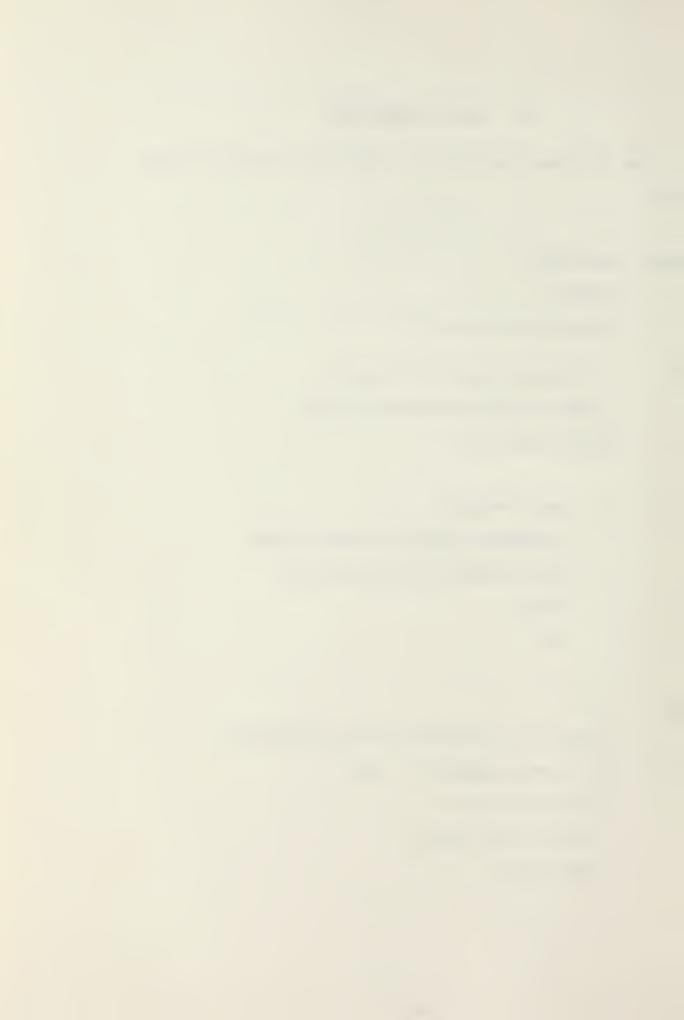
Blank space in column 1.



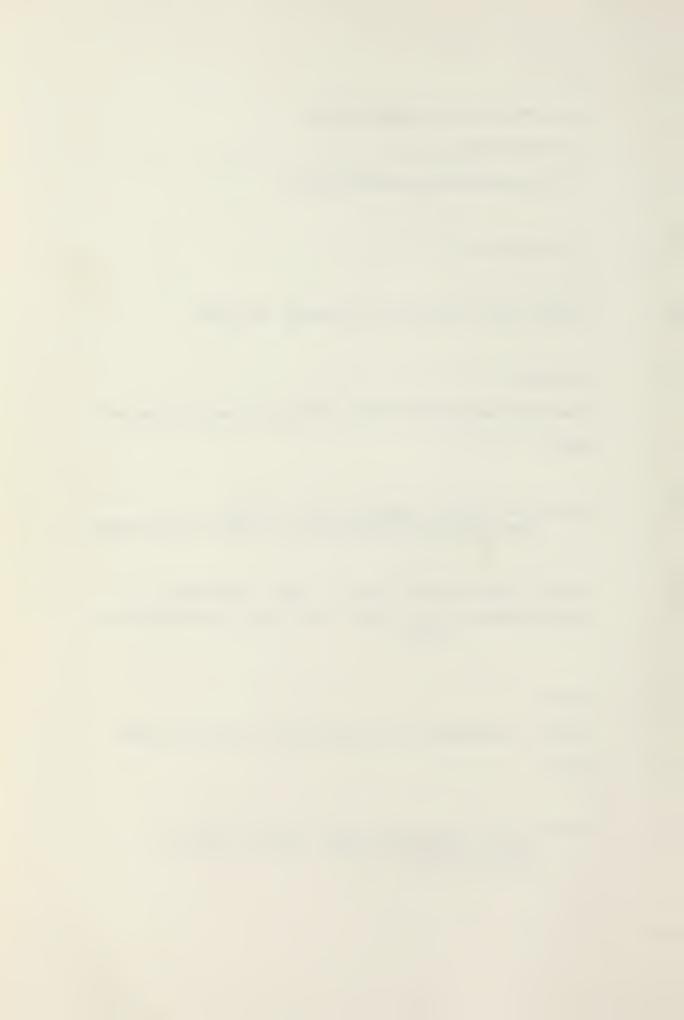
II. INPUT PROCEDURES

The following sequence of cards is necessary to use PSAP1.

```
NOTES IBM CARDS
      COLUMNS
      123456789-----
      // [Standard green job card]
(1)
      // EXEC FORTCLGP, REGION.GO=150K
      //FORT.SYSIN DD *
(2) C
           MAIN PROGRAM
            DIMENSION ZZZ(NZ), DISPD(5,3,NON)
            CALL PSAP1(ZZZ,NZ,DISPD,NON)
            STOP
            END
   /*
(3)
       //LINK.USDD DD UNIT=3330, VOL=SER=DISK02,
       // DISP=SHR,DSN=S1153.PSAP1
       //LINK.SYSIN DD *
        INCLUDE USDD (LOADM)
        ENTRY MAIN
```



```
(4)
          /*
          //GO.FT10F001 DD UNIT=SYSDA,
          // SPACE=(CYL,(3,1)),
          // DCB=(RECFM=VS,BULKSIZE=3520)
(5)
         //GO.SYSIN DD *
(6)
         [PSAP1 title card as it appears on plot]
(7)
          &OPTION
          [&OPTION variables to be initially set or changed]
          & END
          [ADINA or SAP IV geometry data. Title
(8)
               card through element data - remove load cards]
(9)
          [Case identification card - Omit if IDCASE = 0]
          [Displacement data cards - Omit for preprocessing
                        only]
(10)
          &PICT
          [&PICT variables to be initially set or changed]
          &END
          [Additional data as defined by last value of
(11)
               KODE in NAMELIST PICT - Omit if last
               value of KODE = 0]
(12)
         /*
```



Notes:

(1) Standard basic deck set up as described in chapter 3 of reference 8.

```
// [Standard green job card]
// EXEC FORTCLGP,REGION.GO=150K
//FORT.SYSIN DD *
```

(2) Main program.

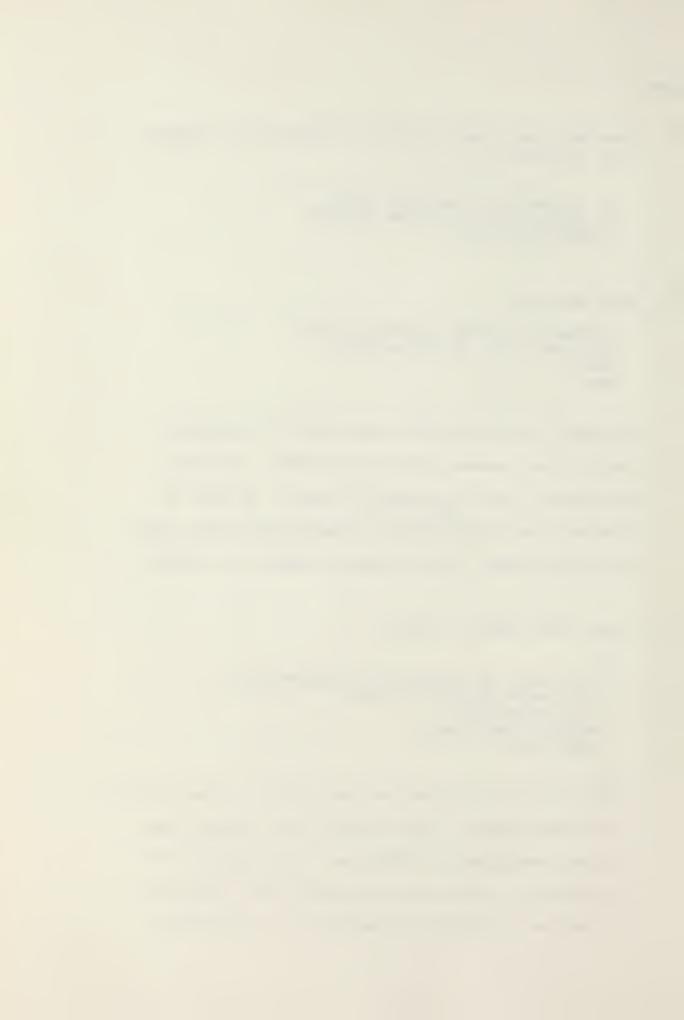
```
DIMENSION ZZZ(NZ),DISPD(5,3,NON)
CALL PSAP1(ZZZ,NZ,DISPD,NON)
STOP
END
```

The main program has two functions: to allocate fast storage space, and to call PSAP1. NON must be greater than the number of nodes. NZ must be greater than 4*NON(7*NON if displacement data cards are to be input. i.e., NUDISP, NVDISP, or NWDISP = 1).

(3) Using load module library.

```
/*
//LINK.USDD DD UNIT=3330,VOL=SER=DISK02,
// DISP=SHR,DSN=S1153.PSAP1
//LINK.SYSIN DD *
INCLUDE USDD(LOADM)
ENTRY MAIN
```

PSAP1 should be precompiled and stored in the machine in a load module. Load modules are a type of user library described in reference 7 and chapter 3 of reference 8. Since PSAP1 requires over one minute to compile, precompiling results in a large time



savings. These cards are subject to change, and the most current version is determined by the user maintaining this library. If PSAP1 is not on a load module, these control cards may be replaced by subroutine PSAP1 (which consists of a box and a half of cards).

(4) Allocation of storage.

```
/*
//GO.FT10F001 DD UNIT=SYSDA,
// SPACE=(CYL,(3,1)),
// DCB=(RECFM=VS,BULKSIZE=3520)
```

PSAP1 uses a slow storage device to store the element connectivity. These cards allocate 3 cylinders as described in chapter 3 of reference 8.

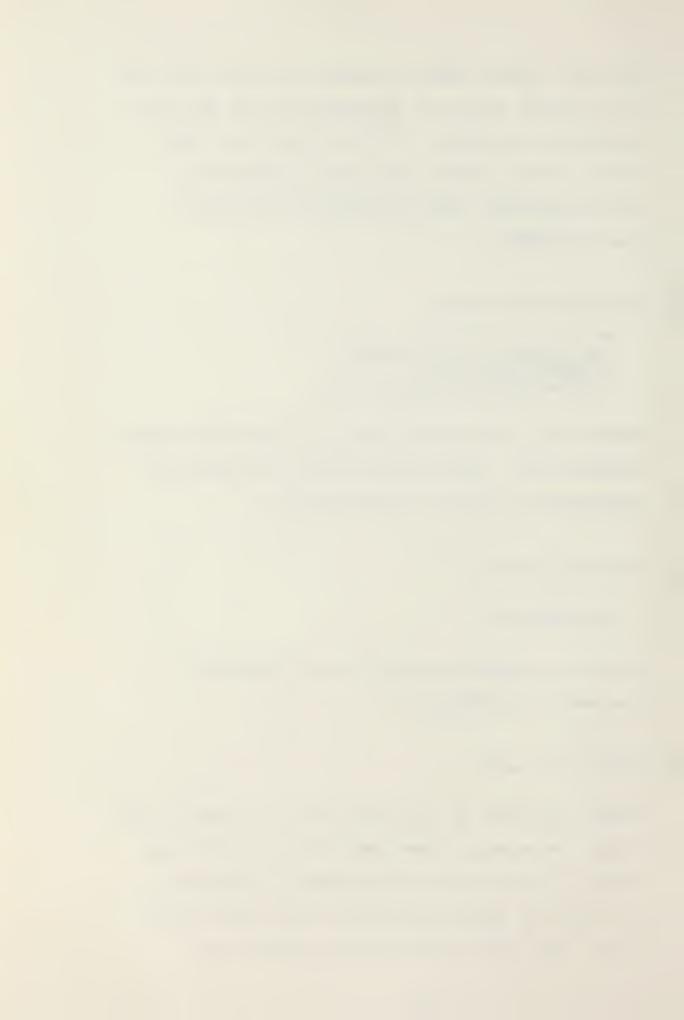
(5) Deck set up card.

```
//GO.SYSIN DD *
```

This is a standard deck set up card described in chapter 3 of reference 8.

(6) PSAP1 title card.

PSAP1 title card is the title that will appear on the graph. Make sure a user identification is on this card. It consists of 80 alphanumeric characters. The first 40 characters will form the first title line. The last 40 will form the second line.



(7) NAMELIST OPTION.

(Note: start in second column)

&OPTION

[&OPTION variables to be initially set or changed]

&END

VARIABLE-DEFAULT	DESCRIPTION
NNDEST-200	Must be equal to the number of nodes.
NUDISP-0	0 - X direction displacements not input.
	1 - X direction displacements input.
NVDISP-0	0 - Y direction displacements not input.
	1 - Y direction displacements input.
NWDISP-0	0 - Z direction displacements not input.
	1 - Z direction displacements input.

(Note: unless displacement data is to be input, allow NUDISP, NVDISP, and NWDISP to default.)

KGEOM-9 Specifies the geometry input format.

1- Subroutine GEOM1 reads in ADINA data deck geometry and connectivity.

2- Subroutine GEOM2 may be supplied by user along with subroutines NSPLAN, NS3DEE and NSTRUS to read nodal data and connectivity in any format.

9- Subroutine GEOM9 reads in SAP IV data deck geometry and connectivity.

KDATA-9 Specifies the subroutine and corresponding method of input for displacement data.

1- Subroutine DATAl, a user supplied subroutine.



2- Subroutine DATA2, a user supplied subroutine.

9- Subroutine DATA9, reads a punched output displacement deck from execution of SAP IV as presented in reference 6. (Note: unless displacement data is to be plotted, allow to default.)

NVALUS-0 Not incorporated, allow to default.

IRESEQ-1 Not incorporated, allow to default.

KPLOT-1 Not incorporated, allow to default.

YSPACE-2.0 Space between plots in the Y direction in inches when successive plots are plotted (i.e., KODE \neq 0). The graph title is plotted both on the top and at the bottom of each set of graphs controlled by a given NAMELIST OPTION. The space between the title and the plot is YSPACE/2.0.

PSIZE-9.0 Paper size in the X direction, in inches. Used in scaling of the plots to insure this dimension is not exceeded. However, when manual scaling (ISCALE = 2; see NAMELIST PICT) this protection is not available, and it is possible to exceed the paper width.

IDCASE-0 0- No identification card precedes the deck of displacement values.

l- Identification card precedes the deck of displacement values.



(8) SAP IV or ADINA data cards.

Here insert the geometry (node coordinates) and element connectivity. This includes the title card through the element data cards; the load cards are removed. For a SAP IV data deck, NAMELIST OPTION variable KGEOM = 9. For an ADINA data deck, KGEOM = 1.

From ADINA deck remove:

- 1. Applied loads data.
- 2. Frequency and mode shape calculations data.

From SAP IV deck remove:

- 1. Concentrated load mass data.
- Element load multipliers.
- 3. Dynamic analysis cards.

Otherwise, these cards are exactly the same as the deck prepared for SAP IV or ADINA. PSAPl is not limited to SAP IV and ADINA. The user may specify any unique format (i.e., KGEOM = 2). In this case, SUBROUTINE GEOM2 must be supplied by the user.

(9) Case ID card and displacement data cards.

PSAP1 is intended to be used essentially for preprocessing. If it is desired to use the postprocessing option, the user is referred to reference 6. Otherwise, omit the case ID card and displacement data.



(10) and (11) NAMELIST PICT.

(Note: start in second column)

&PICT
[&PICT variables to be initially set or changed]
&END

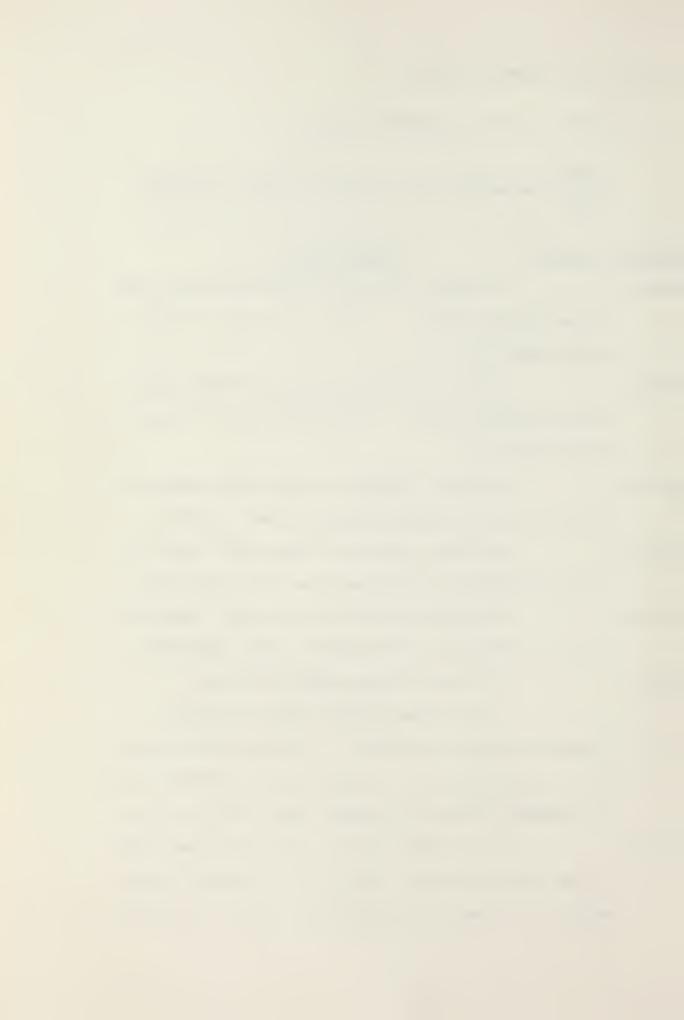
VARIABLE-DEFAULT DESCRIPTION

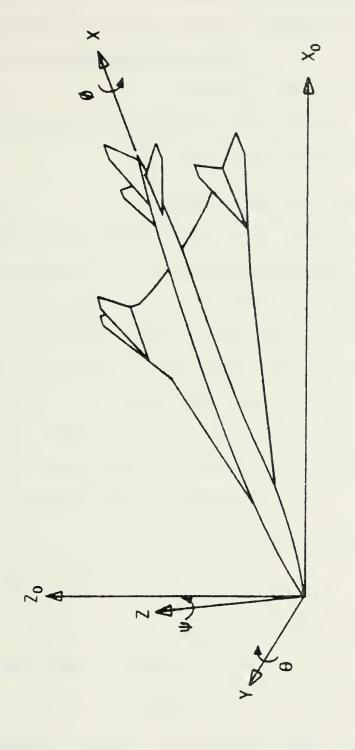
- KHORZ-1 Integer designating the horizontal axes of the viewing plane. $1 = X_0$. $2 = Y_0$. $3 = Z_0$. (See figure 18.)
- KVERT-2 Integer designating the vertical axes of the viewing plane. $1 = X_0$. $2 = Y_0$. $3 = Z_0$. (See figure 18.)
- PHI-0.0 Angular rotation of the model about its

 X axis in degrees (performed 3rd, see figure 18).
- THETA-0.0 Angular rotation of the model about its
 Y axis in degrees (performed 2nd, see figure 18).
- PSI-0.0 Angular rotation of the model about its
 Z axis in degrees (performed 1st, see figure 18).
- NEWFR-1 1- Frame change before plotting.
 - 2- No frame change before plotting.

(Normally allow to default. A frame change resets the Y origin past the previous plot by YSPACE given in NAMELIST OPTION and resets the X origin at 0.0)

as the previous plot. Useful in an assembly graph
where it is desired to examine a mesh in sections





Coordinate systems and Euler angles (rotations) for an oblique orthographic projection shown in X-Z viewing plane. (Taken from reference 4, page 127.) Figure 18.



without losing perspective. See example 3 in Section III of this thesis. ISCALE cannot be zero in the first NAMELIST PICT.

l- Automatic scaling of plot and
computation of proper origin location.

2- User specified origin and scaling.

PLOTSZ-10.0 Maximum dimension desired on completed plot prior to rotation. After rotation it is possible for the maximum dimension in the projected plane to exceed PLOTSZ. The maximum size of the projection is unlimited on the vertical axis but is limited by the paper width (PSIZE in NAMELIST OPTION) on the horizontal axis. If rotation of the model causes the projection to go off the paper, it is rescaled prior to plotting. PLOTSZ is used in scaling only if ISCALE = 1).

XORGN-0.0 X location of the plot origin.
(Used only if ISCALE = 2.)

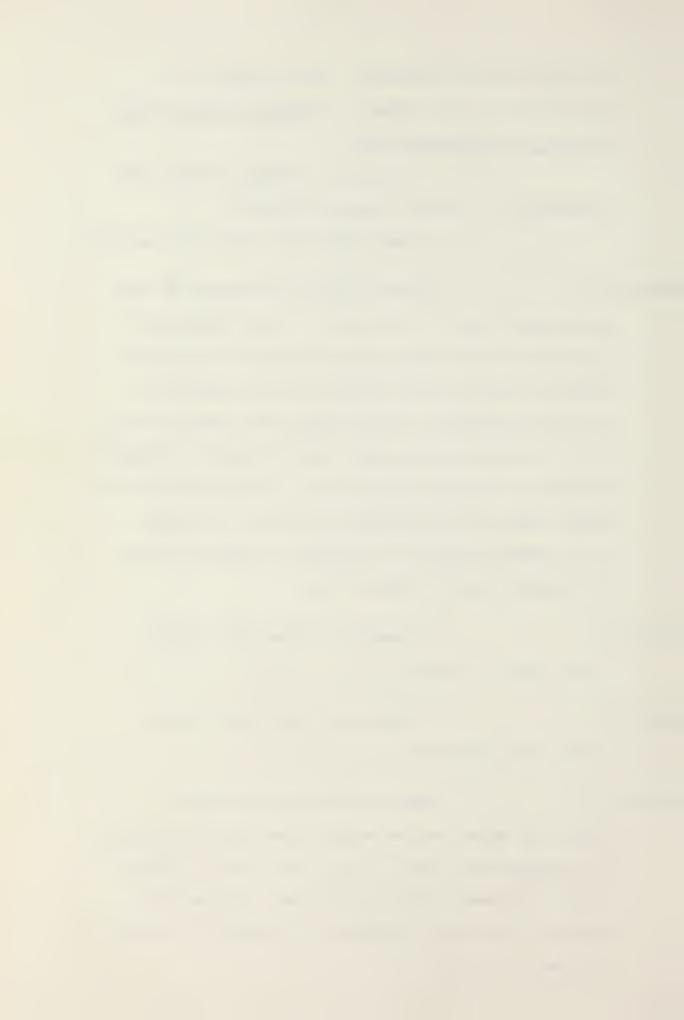
YORGN-0.0 Y location of the plot origin.

(Used only if ISCALE = 2.)

PSCALE-1.0 Model size reduction factor.

PSCALE is equal to the actual model size divided by the desired plot size. It is used only if ISCALE = 2.

(Note that when ISCALE = 2 is used, no rescaling occurs if rotation causes the projection to exceed the paper width.)



NOTAT-0

0- No numbering on plots.

1- Numbering of grid points.

2- Numbering of elements.

XLHT-0.14

Height in inches of the integers specified by NOTAT. It should be a multiple of .07. If XLHT is not a multiple of .07, it will be rounded to the nearest multiple. XLHT has a maximum of .49 and a minimum of .07.

KDISP-0

0- Plot of undeformed structure.

1- Plot of deformed structure.

2- Exploded plot.

3- Displacement represented by

vectors.

KDISP = 1 or 3 represents a form of postprocessing and displacement data must be input in (9). If postprocessing is desired, refer to reference 6.

IDMAG-2 l- Direct magnification of displacement data by DMAGS.

2- Scaling of displacement data to a maximum value of DMAGS.

DMAGS-1.0 Magnification of displacements

(if KDISP = 1 or 3). Reduction factor of elements

(if KDISP = 2).

KSYMXY-0 1- Symmetry about X-Y plane.



KSYMXZ-0

1- Symmetry about X-Z plane.

KSYMYZ-0

1- Symmetry about Y-Z plane.

A plate quadrant with KSYMXZ and KSYMXY equal to 1 would yield a complete plate.

See example 2 in Section III in this thesis.

Note: To develop a partial plot, three methods of segregating elements exist: First, by X, Y and Z cutting planes; second, by node numbers; and third, by element numbers. The next ten variables are used to separate elements into partial plots.

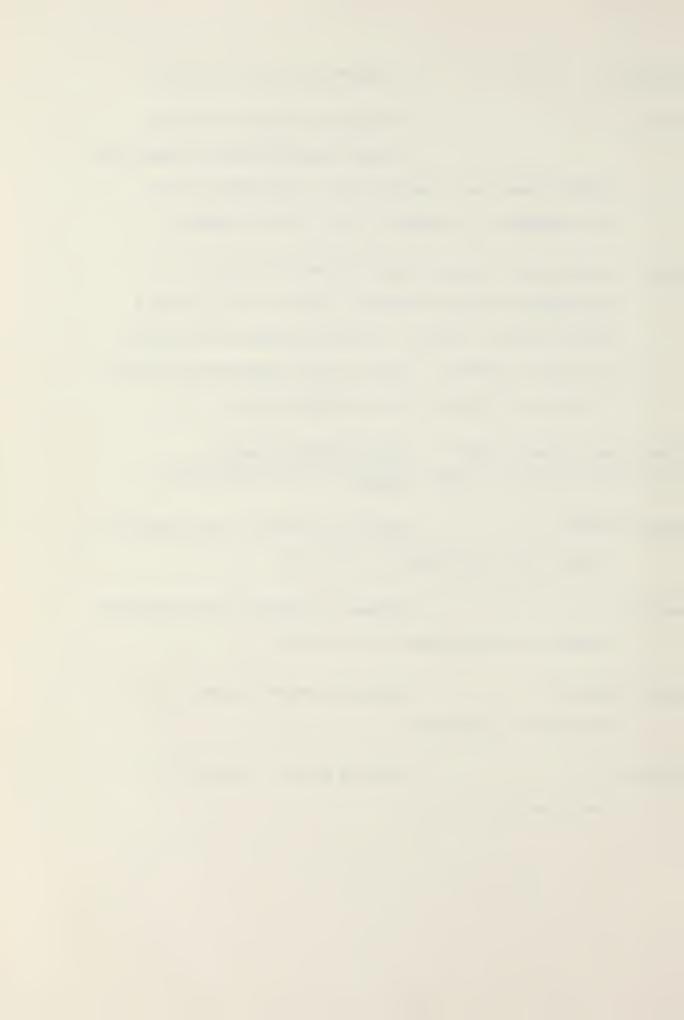
XXMAX,YYMAX,ZZMAX-1.0E20 Local cutting planes XXMIN,YYMIN,ZZMIN-(-1.0E20) Parallel to the principal planes.

NDMAX-9999999 Maximum gridpoint identification number to be included in the plot.

NDMIN-0 Minimum gridpoint identification number to be included in the plot.

NELMAX-9999999 Maximum element number to be included in the plot.

NELMIN-0 Minimum element number to be included in the plot.



KODE-0

Specifies the control option after the plot is completed.

- 0- Last plot, exit from program.
- 1- Read another NAMELIST PICT.
- 2- Read a new set of displacement data. (Postprocessing only.) For KODE = 2, displacement data must be followed by another NAMELIST PICT.

3- Read a complete new set of input data starting with a title card.

For KODE = 1, 2 or 3, additional sections of the deck must be repeated. The deck must end with a NAMELIST PICT having a value of KODE = 0.

Note: A most important point to remember when generating a sequence of plots is that once a parameter has been defined, it retains that value until it is reassigned. For example, if PLOTSZ is assigned a value of 8.0 for the first of a series of plots, and it is not redefined in any subsequent NAMELIST PICT; the value of PLOTSZ will be retained as originally specified. However, when KODE = 3 and a new title, NAMELIST OPTION and problem data are read, all variables in NAMELIST OPTION and NAMELIST PICT are assigned their default values. The



problem starts over in this case. Refer to the flow chart in figure 1 and study the path for different values of KODE.

(12) Delimiter card.

/*

Delimiter card is defined in chapter 3 of reference 8.



III. SPECIAL FEATURES OF PSAPL

A. POSTPROCESSING

Reference 6 contains information and examples on the use of the postprocessor. SAP IV has the capability to punch displacement data cards in an acceptable format for PSAP1 (specifically subroutine DATA9). As of this writing, ADINA does not have this capability, and data cards would have to be punched manually by the user.

B. PARTIAL DATA

Reference 6, on page 30, establishes a procedure by which it is possible to input only a portion of the finite element model for a data check. This feature is valuable in a case where several different people are preparing different parts of a large data base for a problem and desire to check individually their inputs graphically for accuracy. All nodal coordinates for the entire model may be input, or only those that specifically define the portion of the finite element model to be plotted. In either case, all nodal coordinates that define the elements to be plotted must be specified. To use this feature the "element control cards" (described in references 1 and 2) must be modified. For example, if only the connectivity for elements 15 through 50 of a problem are available, the changes below would be made.



1. All SAP IV Elements

All SAP IV element control card changes would have similar changes because columns 6-10 contain the total number of group elements. Columns 66-70 are not used. Thus to plot only elements 15 through 50, make the following changes:

- a. Enter the upper bound (i.e., 50) in columns 6-10.
- b. Enter the lower bound (i.e., 15) in columns 66-70.

2. ADINA Truss, 2D and 3D Elements

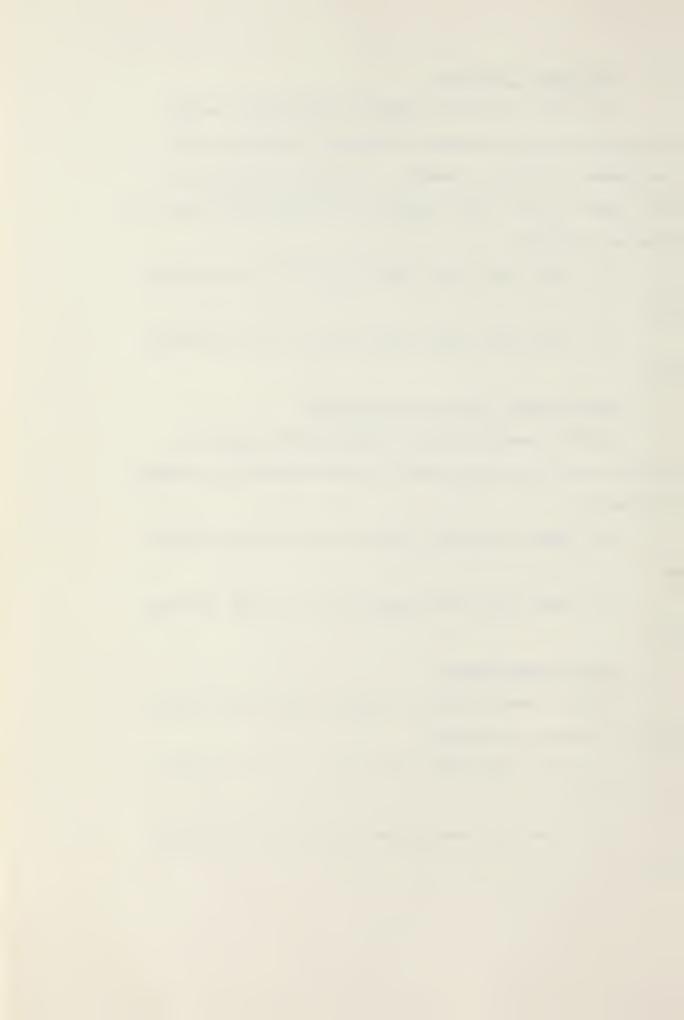
ADINA element control cards for the truss, 2D continuum and the 3D continuum elements would be changed as follows:

- a. Enter the upper bound (i.e., 50) in columns 5-8.
- b. Enter the lower bound (i.e., 15) in columns 53-56.

3. ADINA Beam Element

ADINA element control cards for the beam element would be changed as follows:

- a. Enter the upper bound (i.e., 50) in columns 5-8.
- b. Enter the lower bound (i.e., 15) in columns 65-68.



APPENDIX B

SUBROUTINE PSAP1 LISTING

```
80 ALPHANUMERIC CHARACTERS OF GRAPH TITLE INFORMATION TO BE PRINTED ABOVE AND BELOW THE GRAPH. THE FIRST 40 CHARACTERS WILL FORM THE FIRST TITLE LINE. THE LAST 40 THE SECOND LINE.
                                                                                                                                                                                                                                                                  T = ESTIMATE NUMBER OF GRID POINTS TO BE USED. VALUE MUNICATIONS.

** DEFAULT = 2CO **

POINTS.

** DEFAULT = 2CO **

** DEFAULT = 0 FOR NO CISPLACEMENT DATA IN X-DIRECTION.

** CEFAULT = 0 **

P = 0 FOR NO DISPLACEMENT DATA IN Y-DIRECTION.

** DEFAULT = 0 **

P = 0 FOR NO DISPLACEMENT DATA IN Y-DIRECTION.

** DEFAULT = 0 **

P = 0 FOR NO DISPLACEMENT DATA IN Z-DIRECTION.

** DEFAULT = 0 **

P = 0 FOR NO DISPLACEMENT DATA IN Z-DIRECTION.

** DEFAULT = 0 **

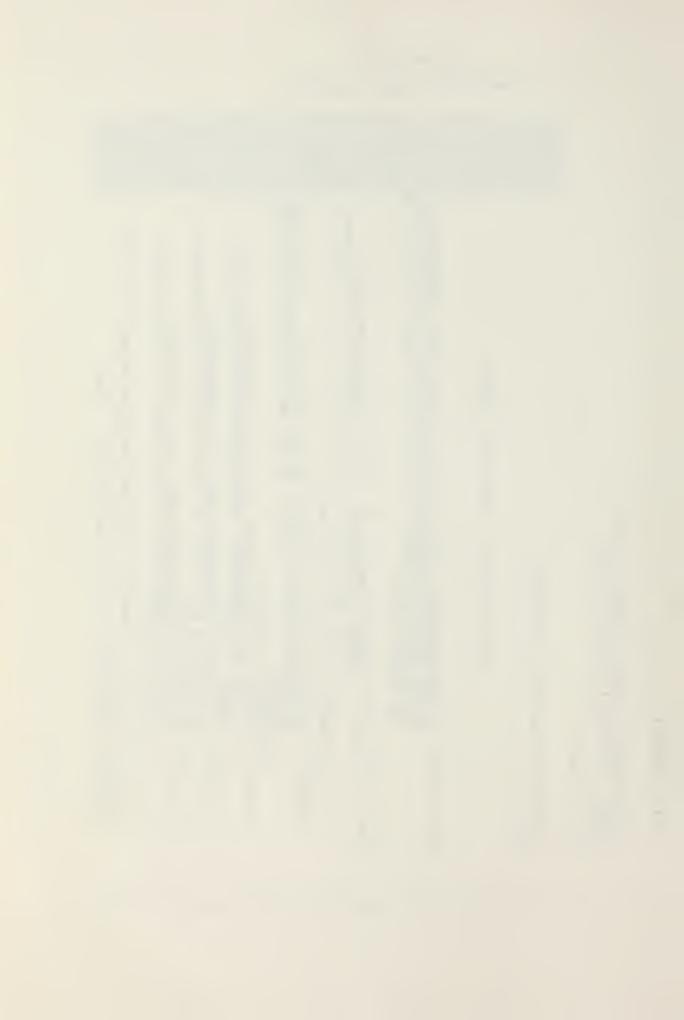
** DEFAULT = 0 **
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NEEDED BY THE PROGRA!
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OR MODEL GEOMETRY.
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DIMENSI
CALL P
STOP
END
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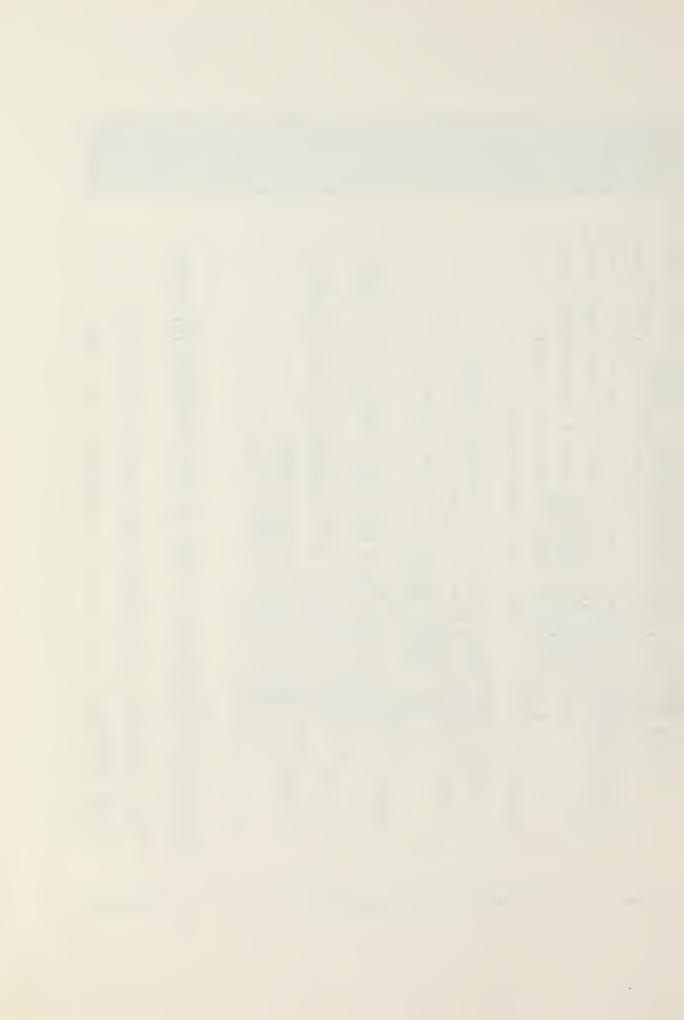
ION ZZZ(1400), DISPD(5,3,200) PSAP1(ZZZ,1400, CISPD,200)

PROGRAM

AIN



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MAR 77
                                 INPUT
                                               DATA
                                                             DATA
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                                                                                                                                                                                                                                                                        F THE FOLLOWING FORMS, PECIFIED IN NAMELIST OPTION
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AND PLOT.
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IV GEOMETRY DATA — MOD
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DISPLACEMENT VALUES.
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= 4 FOR LA
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σ USE IF KGEOM DATA GEOMETRY **>** SAP R EA DS WHICH GECM9 CALL SUBROUTINE

IDENTIFICATION CARD. CASE THIS CARD IS OMITTED IF IDCASE=0 IS SPECIFIED IN EOPTION FOR PRESENT, THIS CARD CONTAINS ANY DESIRED ALPHANUMERIC NFORMATION IN COLS.1-80 WILL NOT APPEAR ON PLOT BUT WILL SPEAR ON PRINTOUT ABOVE DISPLACEMENT DATA

TO BE PLOTTED IS NOW INPUT IN ONE OF THE FOLLOWING FORMS, DEPENDING ON THE VALUE OF KDATA SPECIFIED IN NAMELIST OPTION. CATA

USER THE ВХ KDATA = 1 SUBROUTINE DATA1 WHICH IS PREPARED USE IF

US ER THE ВΥ PREPARED IS DATA5 WHICH KDATA = 5 SUBRCUTINE

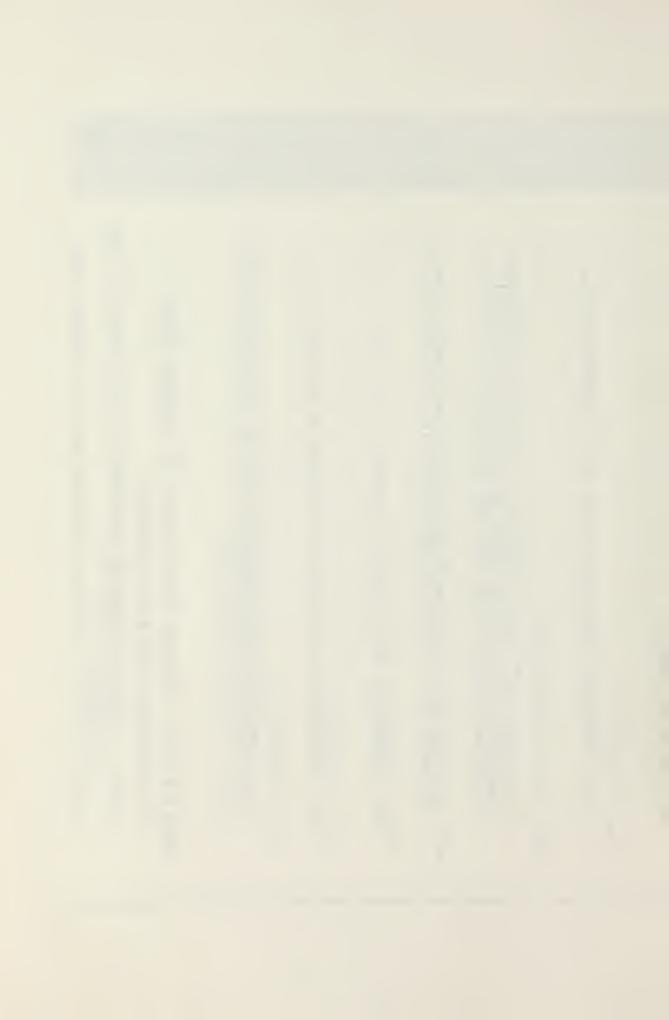
9 11 KDATA L L u OS CALL SUBROUTINE DATA9 WHICH READS SAP IV DISPLACEMENT DATA. A DISPLACEMENT DATA DECK CAN BE PREPAIRED FOR ADINA IN A FORMAT COMPATABLE WITH DATA9.

PLOTS GENERATE 10 - CONTAINS VALUES NEEDED NAMEL IST PICT

INCLUDED-ARE THE FOLLOWING VALUES INTEGER DESIGNATING HOPIZONTAL AXIS OF VIEWING PLANE WHERE 1= x, 2= Y, 3=Z.

DEFAULT = 1 **
INTEGER DESIGNATING VERTICAL AXIS OF VIEWING PLANE, 11 KHORZ

11 ** KVER



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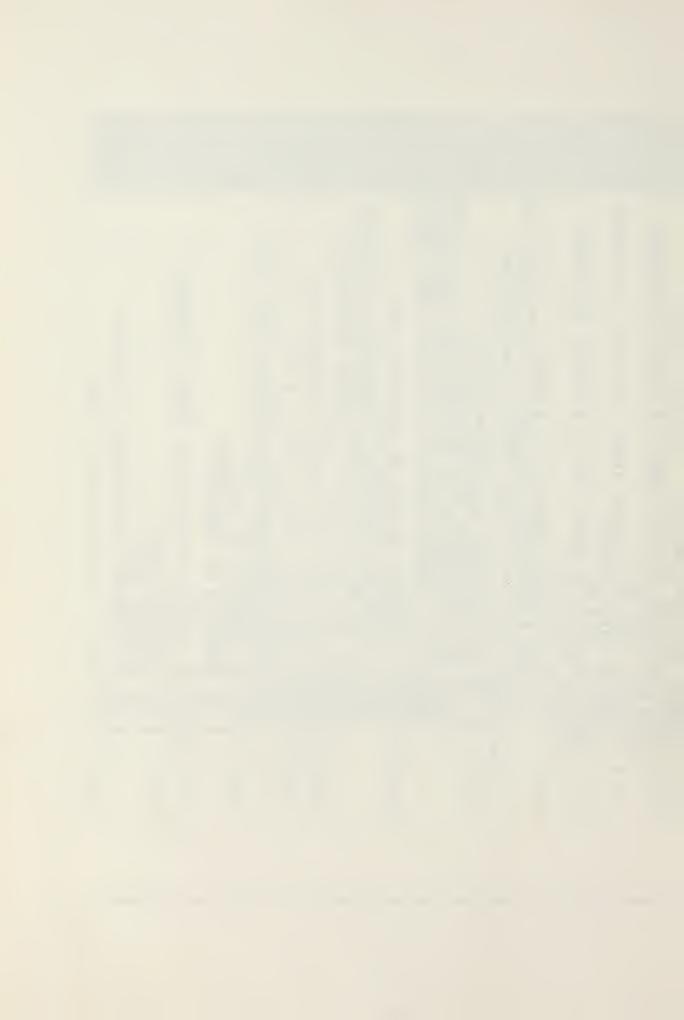
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KSYMXZ = 1 FOP SYMMETRY ABOUT X-Z PLANE.

KSYMYZ = 1 FOR SYMMETRY ABOUT Y-Z PLANE.

KSYMYZ = 1 FOR SYMMETRY ABOUT Y-Z PLANE.

XXMAX,YYMAX,ZZMAX,XXMIN,YYMIN,ZZMIN LOCATE CUTTING PL/

PARALLEL TO **

TO LIMIT PLOT.

** DEFAULT XXMIN=YYMAX=ZZMAX=1.0E+20 **

** DEFAULT XXMIN=YYMIN=ZMIN=-1.0E+20 **

NDMAX = MAXIMUM GRID PT. TO BE INCLUDED IN PLOT.

** DEFAULT = 999999999 **

NELMAX = MAXIMUM ELEMENT NUMBER TO BE INCLUDED IN PLOT.

** DEFAULT = 0 **

NELMAX = MAXIMUM ELEMENT NUMBER TO BE INCLUDED IN PLOT.

** DEFAULT = 599999999 **
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OF ELEMENTS (IF KDISP=2).
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* DEFAULT = 0 **

> ECIFIES CONTROL OPTION AFTER PLOT IS COMP

O, LAST PLCT, EXIT FROM PROGRAM.

1, READ ANOTHER NAMELIST PICT.

2, READ A NEW SET OF DISPLACEMENT DATA, I

CASE IDENTIFICATION CARD IF PRESENT.

3, READ A COMPLETE NEW SET OF INPUT DATA

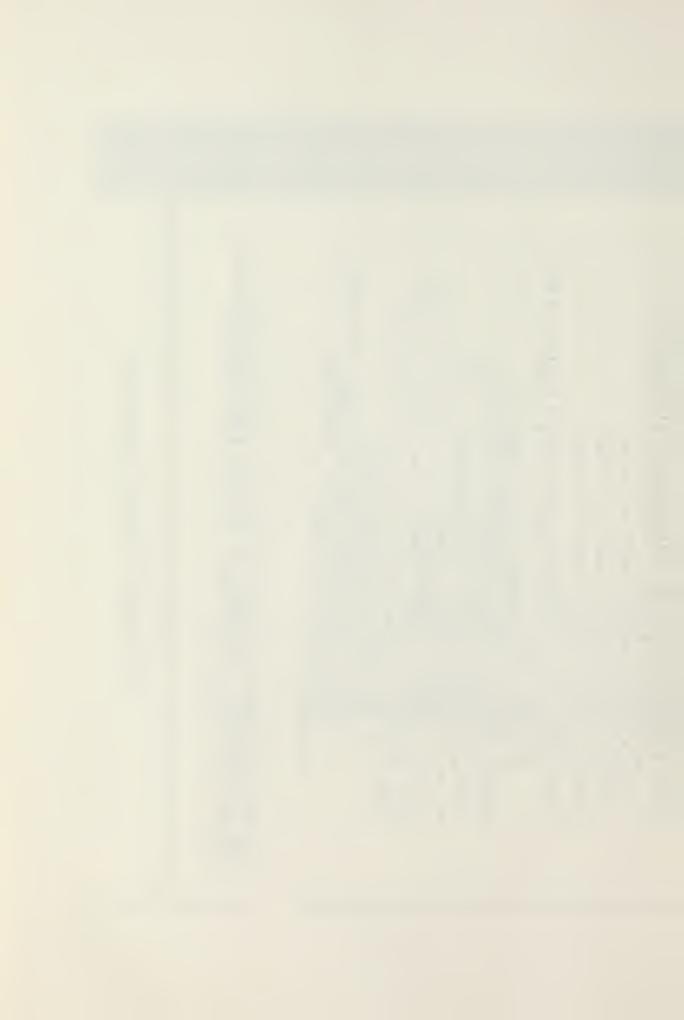
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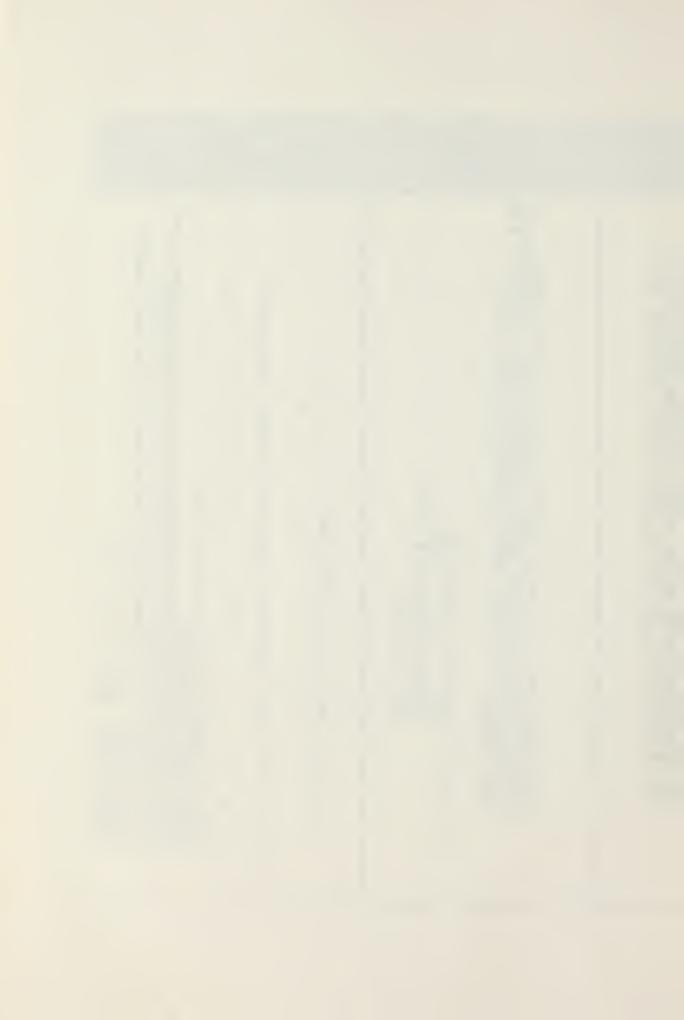
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THE SUBROUTINES USED IN THE ACTUAL CREATION OF PLOTS BY THE CALCOMP MODEL 765 CAN BE FOUND IN NPS TECHNICAL NOTE NUMBER 0211-03, "PLOTTING PACKAGE FOR NPS IBM 360/367".	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	SUBROUTINE PSAPI IS A MODIFICATION TO NAVAL POSTGRADUATE SCHOOL THESIS BY LT. D. M. LOSH, DECEMBER 1976. MODIFICATION C INCLUDED SAP IV 8-21 NODE BRICK ELEMENTS, BOUNDARY ELEMENTS AND C ADINA TRUSS, PLANE, BRICK, BEAM ELEMENTS, AND OTHER MINOR C IMPROVEMENTS.	C MODIFIED BY ADRIAN E. KIBLER JR. C NAVAL PCSTGRADUATE SCHOOL C MONTEREY, CA. C JAN - JUN 1977	(*************************************	C SUBROUTINE PSAP1(ZZZ, NZ, DISPD, NON) C * * * * * * * * * * * * * * * * * * *	C *** THIS IS THE MAIN SUBROUTINE WHICH CALLS OTHER SUBROUTINES C	* * * * * * * * * * * * * * * * * * * *	INTEGER NUMPT, XPT, YPT, ZPT, UPT, WPT COMMON/CDATA/NTIME, NTLC COMMON/CDATA/NTIME, NTLC COMMON/CONTRL/ KGEOM, KDATA, KPLOT, KSYMXY, KSYMXZ, KSYMYZ, NGTAT, XLHT, IKHORZ, KVERT, PHI, THETA, PSI, NEWFR, ISCALE, PLOTSZ, XORGN, YORGN, 2PSCALE, KDI SP, DMAG, KODE COMMON/LIMITS/ XXMAX, YYMAX, ZZMAX, XXMIN, YYMIN, ZZMIN, ND MAX, NDMIN, INELMAX, NELMIN COMMON/CORGN/ YPMAX, YSPACE, PSI ZE COMMON/CORGN/ YPMAX, YSPACE, PSI ZE COMMON/CORGN/ YPMAX, YSPACE, PSI ZE		



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, ABCD2 (10), ABCD3 (10),
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FORMAT (20A4)
WRITE(6,9006) (ABCD1(I),I=1,10),(ABCD2(I),I=1,10)
FORMAT (//,20x,20A4///)
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CCOMMON/SAVEV/ DMAGS, IDMAG
CCOMMON/KOUNT/ NNODE, NNDEST, NUDISP, NVDISP, NWCISF
CCOMMON/VALUES/ NVALUS
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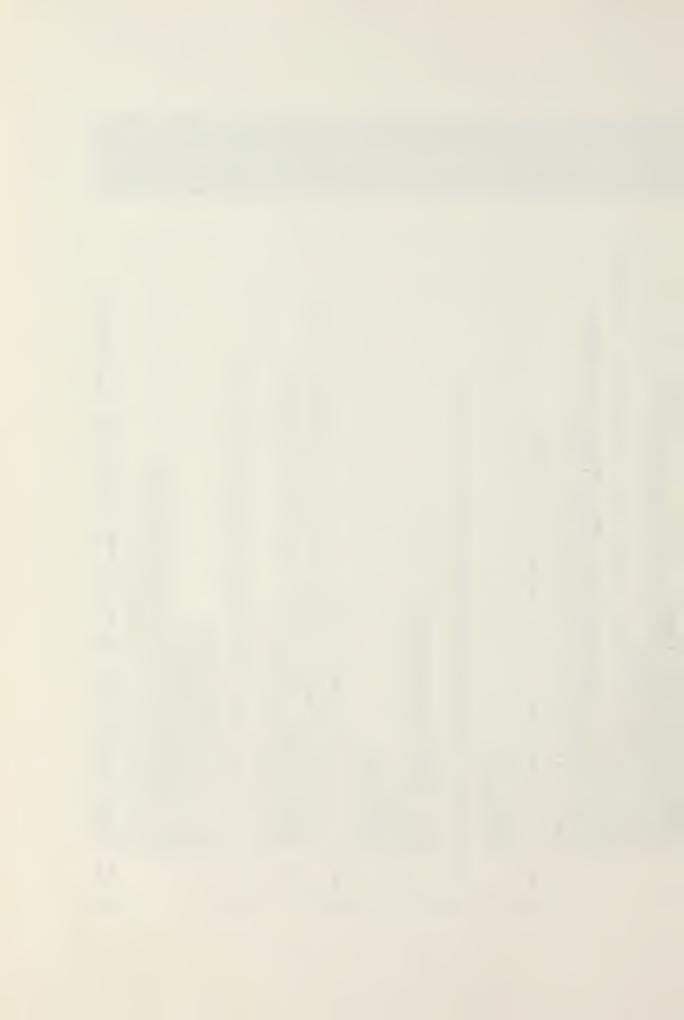
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WPT = VPT +NDEST

NEND = WPT +NDEST -1

LANK CGMMON STORAGE ZZZ REGUIRES AT LEAST '.16, 000003340

CO003340

ALL GEGNS - V/1

LEANK CCMMON STORAGE ZZZ REGUIRES AT LEAST '.16, 000003340

ALL GEGNS - V/1

ALL GEG
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122Z(NUMPT), ZZZ(XPT), ZZZ(YPT), ZZZ(ZPT), ZZZ(UPT), ZZZ(VPT), ZZZ(WPT))

READ(5,9004, END=999) (ABCD3(I), I=1,10), (ABCD4(I), I=1,10)

READ(5,9006) (ABCD3(I), I=1,10), (ABCD4(I), I=1,10)

CONT INUE

CALL ZEROE

(ALL DATA1

I (ZZZ(NUMPT), ZZZ(XPT), ZZZ(YPT), ZZZ(ZPT), ZZZ(UPT), ZZZ(WPT))

I (ZZZ(NUMPT), ZZZ(XPT), ZZZ(YPT), ZZZ(ZPT), ZZZ(UPT), ZZZ(WPT))
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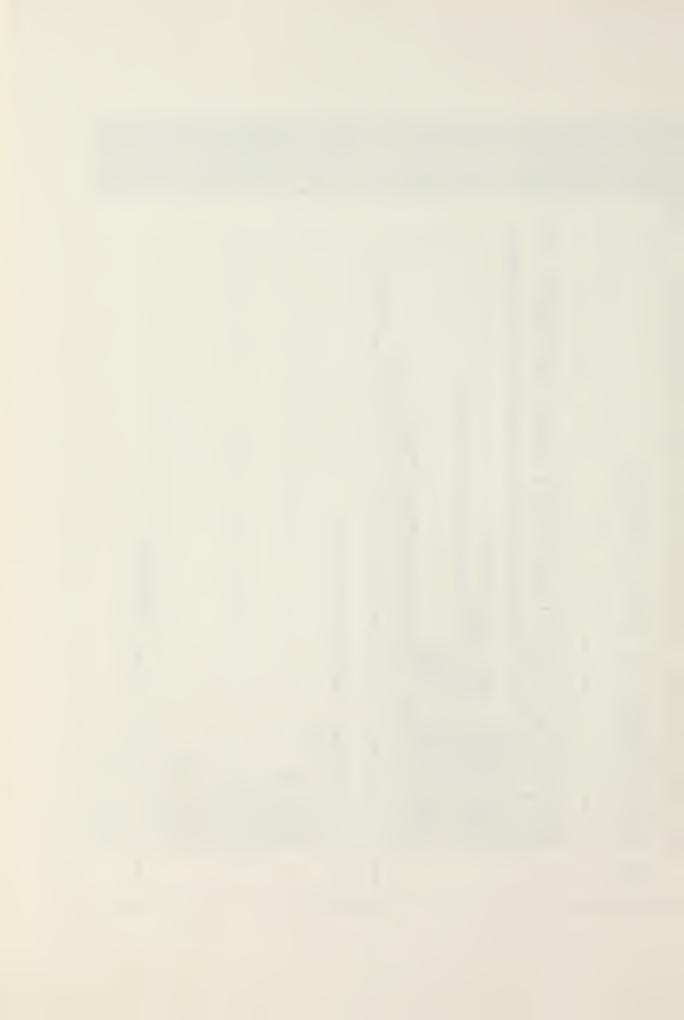
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                                                       CALL CALPLI(0.0, YPMAX+YSPACE/2.0)
CALL CALPLI(0.3, 0.0, 3)
CALL CALPLI(0.0, 1.0, 2)
CALL CALPLI(0.0, 1.62, 2)
CALL CALPLI(9.0, 1.62, 2)
CALL CALPLI(9.0, 1.62, 2)
CALL NOTATE(0.8, 1.31, 21, ABCD1, 0.2)
CALL NOTATE(0.8, 1.0, 21, ABCD2, 0.0)
ILOOP=
CALL CALPLI(0.0, 1.62+YSPACE, -3)
IF(KODE EQ.3) GO TO 500
WRITE(6,9008)
IF(KODE CALP)
RETURN
CALL PSIOP
RETURN
SCALL ERROR(2)
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WRITE(6,0PTIO)
WRITE(6,9010)
RETURN
CALL ERROR(3)
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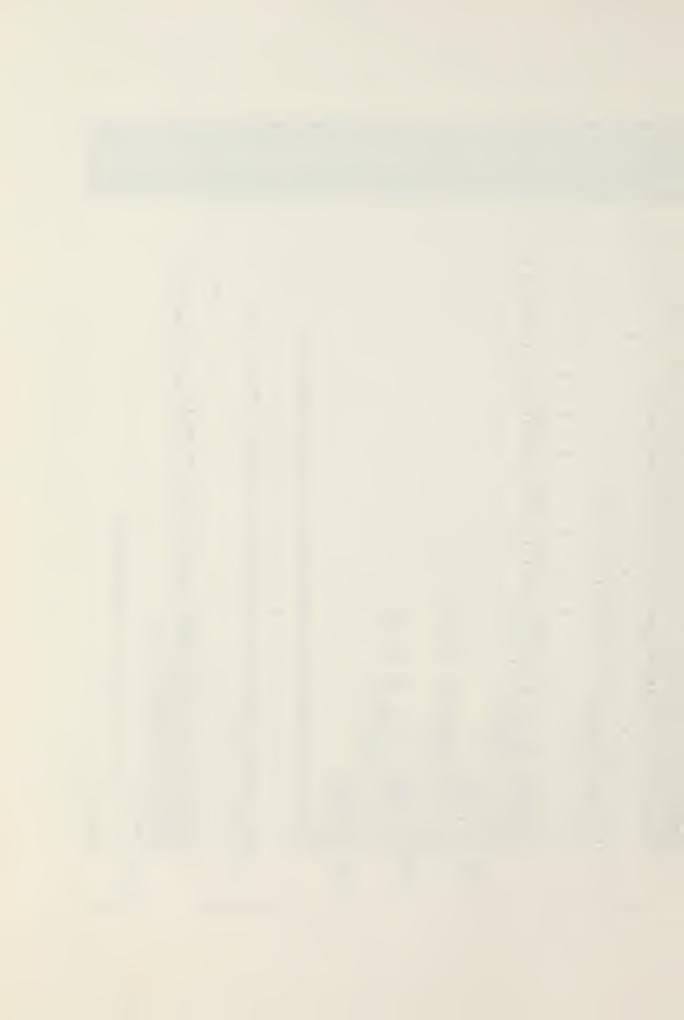
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E(6,9010) I,NUMEL,(NODE(J),J=1,4),(NODE(J),J=9,12
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  FORMAT (//,5x, RESEQUENCED, 4x, USER INPUT')

LEX, GRID PCINT',

LEX, LOUNBER',

LEX, LOUNBE
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. EQ. 12) GO TC 40

. 9010) I, NUMEL, (NODE(J), J=1, NEND)

1X, I4, 11X, I4, 9X, 2015)
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IF(NUDISP.NE.O) U = LPT(I)

V = 0.0

IF(NVDISP.NE.O) V = VPT(I)

W = 0.0

IF(NWDISP.NE.O) W = KPT(I)

WRITE(6.18) I,NUMPT(I),U,V,W

SETURN
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FORMAT(///,5x,OISPLACEMENTS
WRITE(6,17)
DO 230 I=1,NNODE
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ELEMENT', 8X,' ELEMENT',
NUMBER', 9X,' NUMBER', 7X,
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IF(NEND.EQ
WRITE(6,90
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IF(NUMPT(I).GT.0) NUMPT(I)=-NUMPT(I
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YMCVE=YPMAX+YSPACE

O, YMCVE, -3)

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IF (ILCODP.EG.0) G

IF (NEWFR.EG.1) Y
CALL CALPLT(0.0)
CONTINUE
CONTINUE
IF (ISCALE.NE.0)
IF (ISCALE.NE.0)
IF (ISCALE.NE.0)
IF (ISCALE.NE.0)
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CALL CALE.EG.1)
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NUMPT(ND) = IABS (NUMPT(ND))

IF (NUMPT(ND) LT.NDMIN.GR.NUMPT(ND).GT.NDMAX) GO TO

CONTINUE

I = KHGRZ

J = KYGRZ

DO 20 N=1.NEND

IF (XPT(ND) CT.XXMAX) GO TO 100

IF (XPT(ND) LT.XXMIN) GO TO 100

XOISP (N) = 0.0

XOISP (N) = 0.0

XOISP (N) = 0.0

XOISP (N) = XPT(ND)

IF (XDISP EQ.1 AND NWDISP NE.0) XDISP (N) = WPT(ND)

IF (XDISP EQ.1 AND NWDISP NE.0) ZDISP (N) = WPT(ND)

X(N) = XSIGN* (XPT(ND) +YDISP (N) *DMAG+XSHIFT) /PSCALE

Y(N) = YSIGN* (XPT(ND) +YDISP (N) *DMAG+YSHIFT) /PSCALE
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= VPT(ND)
= WPT(ND)
= MPT(ND)
IFT)/PSCALE
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2.AND.KSYMYZ.NE.1) GO TO 520
2.AND.KSYMYZ.EQ.1) XSIGN = -1.0
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                                                                              500
                                                                                                                                                                                                                                                                                                                                           REWIND 10
CONTINUE
READ(10, END=1000) NEND, NUMEL, (NODE(J),
IF(NUMEL-LT, NELMIN.OR.NUMEL.GT.NELMAX)
DO 10 I = 1, NEND
ND = NODE(I)
IF(NODE(I).EQ.0)GO TG 10
                                                                                                                                                                                                                                                                                                      0 F
                                                                                                                                                                                                                                                                                                        COORDINATES
                                                                                                                                                              GO TO
YSIGN
                                                                              60 TO
ZSI6N
SYMMETRY
                                      ZSIGN = +1.0

DO 500 II=1.2

IF(II.EQ.2.AND.KSYMXY.NE.1) G

IF(II.EQ.2.AND.KSYMXY.EQ.1) Z

YSIGN = +1.0

DO 510 J=1.2

IF(J).EQ.2.AND.KSYMXZ.EQ.1) Y

XSIGN = +1.0

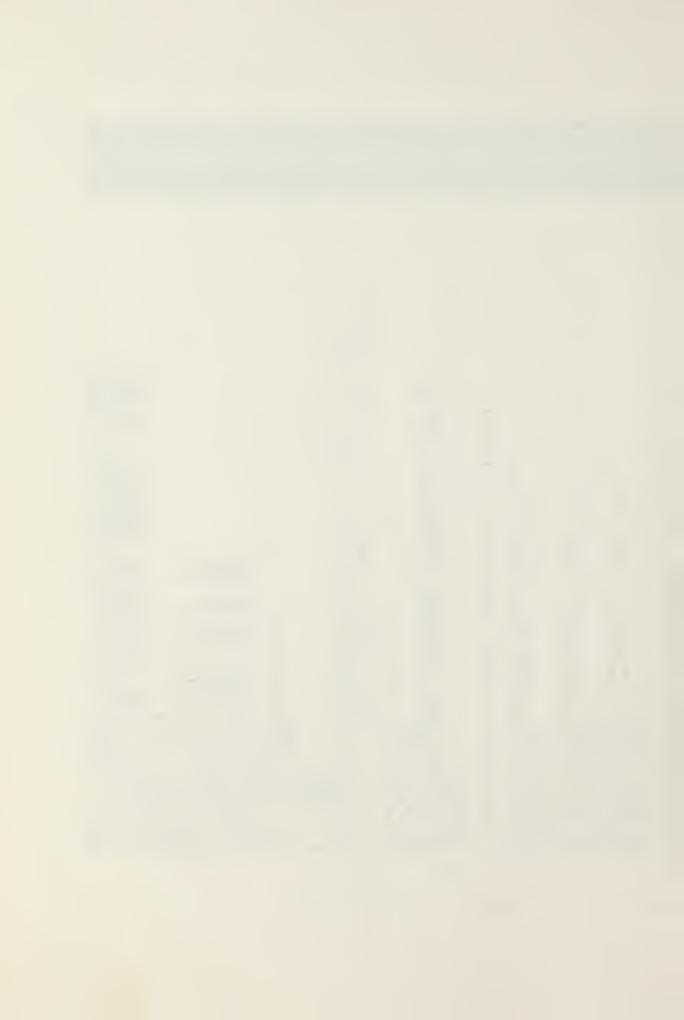
DO 520 KK=1.2

IF(KK.EQ.2.AND.KSYMYZ.NE.1) G

IF(KK.EQ.2.AND.KSYMYZ.NE.1) G

IF(KK.EQ.2.AND.KSYMYZ.NE.1) G

IF(KK.EQ.2.AND.KSYMYZ.NE.1) G
                                                                                                                                                                                                                                                                                                         DETERMINE PROJECTED
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SUBROUTINE NUMBER APPLIES ONLY TO CALCOMP
CONTINUE
IF(NOTAT.EQ.2) CALL NUMBER(XCENT, YCENT, XLHT, AL, 0.0,-1)
SIGN*(ZPT(ND)+ZDISP(N)*DMAG+ZSHIFT)/PSCALE
                                                                                1,2)*Y(N)+A(I,3)*Z(N),2)*Y(N)+A(J,3)*Z(N)
                    CALL XFLOD(NEND,X,Y,Z,NODE
                                                                                                                                                  XROT(N) = XROT(N) + DELX

YROT(N) = YROT(N) + DELY

IF (YROT(N) + GT.YPMAX) YPMAX=YROT(N)

IF (NOTAT.NE.2) GO TO 29

XCENT = XCENT/FND-(6.0/7.0)*XLHT

YCENT = YCENT/FND-XLHT/2.0

XCENT = YCENT/FND-XLHT/2.0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                    ELEMENT
                                                                                                                                                                                                                                                                                                                                                                                                             CONTINUE
CALL CALPLT(XROT(1), YROT(1),3)
CALL CALPLT(XROT(2), YROT(2),2)
GO TO 430
                                                                                                                                                                                                                                                                                                                                                                                                                                                                   PLANE
Z(N) = ZSIGN*(ZPT(ND)+ZDISP

CONTINUE

IF(KDISP.EQ.2) CALL XFLOD(N

XCENT = 0.0

YCENT = 0.0

FND=0.0

DO 25 N=1, NEND

IF(NODE(N).EQ.0) GG TG 25

XROT(N) = A(1,1)*X(N)+A(1,2)

YROT(N) = A(1,1)*X(N)+A(1,2)

YROT(N) = A(1,1)*X(N)+A(1,2)

YROT(N) = A(1,1)*X(N)+A(1,2)

YROT(N) = A(1,1)*X(N)+A(1,2)

YCENT = XCENT+XROT(N)

YCENT = YCENT+XROT(N)

XROT(N) = XCENT+XROT(N)

YCENT = YCENT+YROT(N)

XROT(N) = XCENT+YROT(N)
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IF (NEND-EQ-2) GO TO 28
IF (NEND-EQ-4) GO TO 32
IF (NEND-EQ-8) GO TO 32
IF (NEND-EQ-12) GO TO 32
IF (NEND-EQ-20) GO TO 32
CALL ERROR(4)

ELEMENTS

TO PLOT

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***TO PLOT 2 NODE ELEMENT

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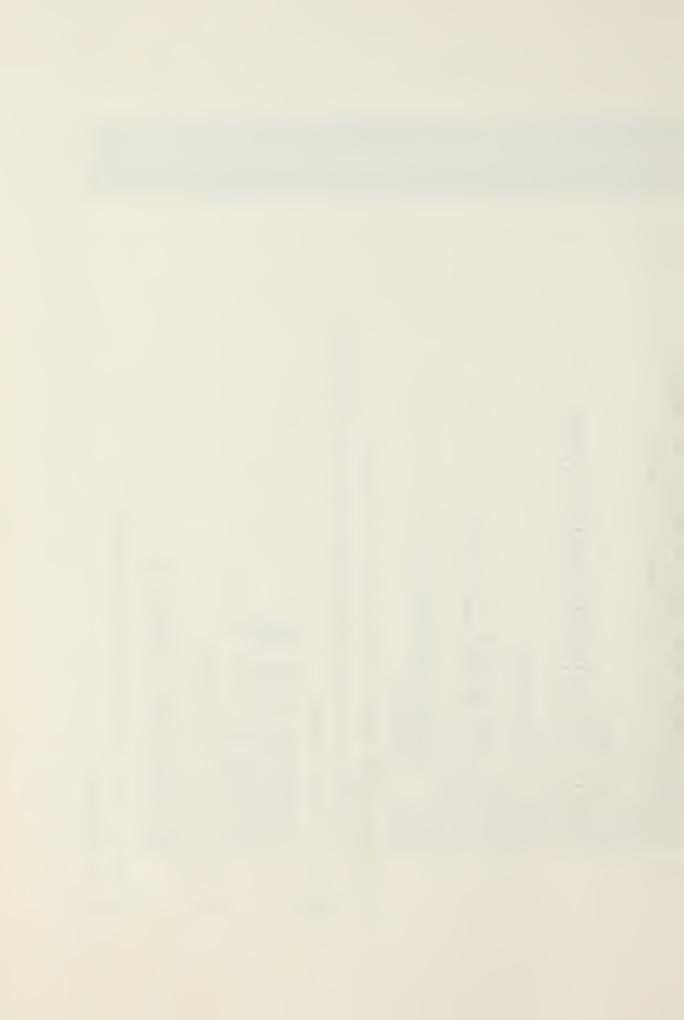
80

AND 4 NODE

TO PLOT 3 CONT INUE

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4-8 NODE PLANE AND 8-20 NOCE BRICK ELEMENTS
LINE ONLY APPLIES TO THE CALCOMP PLOTTER
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               NE.O) CALL CURVE(XP,YP,N)
,YP,N,1,1)
                                                                                                                   CONTINUE
LP=1
DO 330 NP=2,6,4
NP2=NP+2
CALL CALPLT (XROT (LP), YROT (LP),3)
DO 325 MP=NP,NP2
CALL CALPLT (XROT (MP),YROT (MP),2)
CALL CALPLT (XROT (MP),YROT (MP),2)
                                                                                                                                                                                                                                                                                                                                                                * NO.

$40 CONTINUE

LP=1

KP=8

NP2=NP+2

CALL CALPLT(XROT(LP), YROT(LP), 3)

CALL CALPLT(XROT(LP), 3)

KP=KP+1

N=2

CALL WHERE(XP(1), YP(1))

YP(2)=YROT(MF)

YP(2)=YROT(MF)

YP(3)=YROT(KP)

YP(3)=YROT(KP)

YP(3)=YROT(KP)

TF(NODE(KP).NE.O) CALL CUF

CALL LINE(XP).NE.O)

CALL LINE(XP).NE.O
                                                                                                                                                                                                                     CALL CALPLT(XROT(LP), YROT(LP), 2)
LP=LP+4
CONTINUE
335 NP=1, 4
NP4=NP+4
CALL CALPLT(XROT(NP), YROT(NP), 3)
CALL CALPLT(XROT(NP), YROT(NP4), 2)
CONTINUE
TO 430
CALL CALPLT(XROT(1), YRCT(1),3)
DO 305 NP=2,NEND
CALL CALPLT(XROT(NP),YROT(NP),2)
                                                    CALPLT (XROT(1), YROT(1), 2)
430
                                                                                            BRICK
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                                                                                                                                                                 CURVE(XP,YP,N)
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IF (NUMPT(ND).LT.NDMIN.OR.N

IF (XPT(ND).LT.XYZMAX(1)) 6

IF (XPT(ND).LT.XYZMIN(1)) 6

IF (YPT(ND).LT.XYZMIN(1)) 6

IF (YPT(ND).LT.XYZMIN(2)) 6

IF (YPT(ND).CT.XYZMIN(2)) 6

IF (ZPT(ND).CT.XYZMIN(2)) 6

IF (ZPT(ND).CT.XYZMIN(2)) 6

IF (ZPT(ND).LT.XYZMIN(2)) 6

IF (ZPT(ND).LT.XYZMIN(2)) 6

IF (ZPT(ND)+XZMIN(2)) 6

IF (ZPT(ND)+XZMIN(2)) 6

IF (ZPT(ND)+XZMIN(2)) 6

IF (ZPT(ND)+ZZMIN(2)) 6

ZOISP(1) = 0.0

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ZOISP(1) = 0.0
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N=2

CALL WHERE (XP(1),

XP(2) = XROT(LP)

XP(3) = XROT(KP)

YP(3) = YROT(KP)

IF(NODE(KP).NE.O)

CALL LP+4

IF(NEND.EQ.12)

CONTINUE

NP4=NP+4

NP4=NP+4

NP4=NP+16

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NP6=NP+16

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GARROW(XROT(1), YROT(2), YROT(2), 1, XARW, YARW)

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IF(NVDISP.NE.O) YDISP(1) = VPT(ND)

X(2) = XSIGN*(XPT(ND) + XDISP(1) * DMAG+XSHIFT)

X(2) = ZSIGN*(YPT(ND) + YDISP(1) * DMAG+XSHIFT)

Z(2) = ZSIGN*(ZPT(ND) + YDISP(1) * DMAG+ZSHIFT)

I = KHGRZ

J = KVERT

DO 605 N=1,2

XROT(N) = A(I,1) * X(N) + A(I,2) * Y(N) + A(I,3) * Z(XROT(N)) = A(J,1) * X(N) + A(J,2) * Y(N) + A(J,3) * Z(XROT(N)) = XROT(N) + DELX

XROT(N) = XARW/3.0

CALL GARROW(XROT(1), YROT(1), XROT(2), YROT(2)

CONTINUE

ZO CONTINUE
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BS(NUMPT(I))
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NUMPT(I)=IAB
CONTINUE
RETURN
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SUBROUTINE
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COMMON/CONTRL/ KGEOM, KDATA, KPLOT, KSYMXY, KSYMXZ, KSYMYZ, NOTAT, XLHT, 1KHORZ, KVERI, PHI, THETA, PSI, NEWFR, ISCALE, PLOTSZ, XORGN, YORGN, COMMON/SAVEV/ DMAGS, IDMAG, NODE, NVDISP, NWEISP COMMON/KOUNT/ NNODE, NNDEST, NUDISP, NVDISP, NWEISP COMMON/KOUNT/ NNODE, NNDEST, NUDISP, NVDISP, NWEISP GO TO (10,20), IDMAG CONTINUE DMAG = DMAGS

GO TO (10,20), IDMAG CONTINUE CONTINUE
                                                                                       00
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)*R*(R-1.0)/2.0-Y(3)*(R+1.0)*(R-1.0)+Y(2)*R*(R+1.0)/2.

)*R*(R-1.0)/2.0-X(3)*(R+1.0)*(R-1.0)+X(2)*R*(R+1.0)/2.
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IF(NUDISP.EC.0) GO TC 500
IF(ABS(UPT(I)).GT.DMAX) DMAX = 1F(ABS(VPT(I)).GT.DMAX) DMAX = 1F(NWDISP.EQ.0) GO TC 501
IF(NWDISP.EQ.0) GO TC 502
IF(NW
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CONTINUE
RETURN
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      (I)=YP(I
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                                                                                                                                    =R+0.1
                                                                                                                                                                                                                                               SUBROUT INE
                                              R=-1.0

DO 200 I=1.7

YP(I)=Y(I)*X

XP(I)=X(I)*X

R=R+0.1
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                                                                                                                                                                              N=21
RETURN
END
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     J = KVERT

DMAX = 0.0

DO 5 N=1,3

VDUM = ABS(XYZMAX(N)-XYZMIN(N))

IF(VDUM,GT.DMAX) DMAX = VDUM

5 CONTINUE

PSCALE = DNAX/PLOTSZ

DO 10 N=1,2

DO 10 N=1,2

N = XYZMIN(1)

X = XYZMIN(1)

TE(1, FC 2) X = XYZMAX(1)
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IF(L *EC*2) X = XYZMAX

Y = XYZMIN(2)

Z = XYZMIN(2)

Z = XYZMIN(3)

Z = XYZMAX

XROT = A(1,1) *X+A(1,2)

YROT = A(1,1) *X+A(1,2)

YROT = A(1,1) *X+A(1,2)

YROT = XROT

XRMAX = XROT

YRMIN = XROT

YRMAX = YROT

YRMAX = YROT

IF(XROT *CT*XRMIN) YRMI

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IF(NEND.NE.3) GO TO 2

CONTINUE

A = SQRT((X(1)-X(3))*:

B = SQRT((X(1)-X(3))*:

AC1 = A/(A+B+C)

AC2 = B/(A+B+C)

AC3 = C/(A+B+C)

XOC = AC1*X(1)+AC2*X(2)

YOC = AC1*X(1)+AC2*X(2)

CONTINUE
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FND=FND+1.0

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LPLT(XA,YA,2)

LT.2) GO TO 1000

2+(C*XHEAD-S*(-YHEAD))

2+(C*XHEAD-S*(-YHEAD))
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CALPLT(X2, Y2, 2)
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-3) GO TO 100
PLT(X2,Y2,2)
-4) GO TO 100
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XA = X2+(C1)
YA = Y2+(C1)
YB = Y2+(C2)
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XC = X2+(-S*YHEAD

YC = Y2+(+C*YHEAD

CALL CALPLT(XC,YC,

IF(NC,LT,5) GO TO

XD = X2+(-S*(-YHEAL

YD = Y2+(+C*(-YHEAL

CALL CALPLT(XD,YD,2

CONTINUE

CALL CALPLT(XD,YD,2

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0 CONTINUE

60 TO (21,22,23,24), MTYPE

CALL ADTRUS

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CALL ADPLAN

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ALL AD3CEE

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GO TO 1000 CONTINUE WRITE(6,9004)	FORMAT(//,1X, ABNORMAL TERMINATION GO TO 1000	CONTINUE WRITE(6,9005) FORMAT(//,'ABNORMAL TERMINATION IN GU TO 1000	CONTINUE WRITE(6,9006) FORMAT(//,'ABNORMAL TERMINATION IN GO TO 1000	CONTINUE WRITE(6,9007) FORMAT(//,'ABNORMAL TERMINATION IN GOLTO 1000	WRITE(6,9008) FORMAT(//, 'ABNORMAL TERMINATION IN GO TO 1000	WRITHE WRITHE FORMAT 600 101	CONTINUE WRITE(6,9010) FORMAT(7/, ABNORMAL TERMINATION IN A GO TO 1000	CONTINCE WRITE(6,9011) FORMAT(7/, ABNORMAL TERMINATION IN N GO. TO. 1000	CONTINUE WRITE(6,9012) FURMAT(//,'ABNGRMAL TERMINATION IN GD TO 1000	WAY I TING FORMET (6	RITE(CORMAT(CORM	5 CONTINUE 60 TO 100 6 CONTINUE
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REAU(5,9006) CT,N,XPT(N),YPT(N),ZPT(N),KN
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NUMNP = TOTAL NUMBER OF NODE POINT
NELTYP = NUMBER OF ELEMENT GROUPS
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FORMAT(215)
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READ ELEMENT CENTROL CARDS

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(1415)
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NPAR = ',2015///
                                                                                 IF(CT.NE.CTEST) GO TC 20
R=XPT(N)
XPT(N)=R*SIN(ZPT(N)/57.
ZPT(N)=R*COS(ZPT(N)/57.
CONTINUE
NUMPT(N)=N
IF (NOLO.EQ.O) GO TC 50
    9006 FURMAT(A1,14,30X,3F10.C,15)
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                                                                                                                                                                                                                                                                                       | F (KN.EQ.0) GO TO 50 | NUM=(N-NOLD)/KN | NUMN=(N-NOLD)/KN | NUMN=(N-NOLD)/KN | NUMN=(XPT(NOLD))/DZ=(XPT(N)-XPT(NOLD))/DZ=(XPT(N)-XPT(NOLD))/DZ=(XPT(N)-XPT(NOLD))/DZ=(XPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(KK)+DX/YPT(K)=XPT(K)=XPT(KK)+DX/YPT(K)=XPT(K)=XPT(KK)+DX/YPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(K)=XPT(
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FORMAT(1415)
WRITE(6,9010)
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MTYPE=NPAR(1)
CALL ELTYPE(M
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                              COMMON/GCONT/NUMNP,NFAR(20),NELTYP,NUMEL

NUME = NPAR(2)

NUMMAT = NPAR(2)

NUMMAT = NPAR(3)

*** READ MATERIAL PROPERTY CARDS (DUMMY)

CO 10 I = 1,NUMMAT

READ(5,1001) DUMMY

10 CONTINUE

**** READ ELEMENT LOAD MUL. (DUMMYI)

CONTINUE

**** READ ELEMENT CONNECTION INFORMATION OR GEN

** READ ELEMENT CONNECTION INFORMATION OR GEN

OO READ(5,1004) M, II JJ,MTVP,TEM,KK

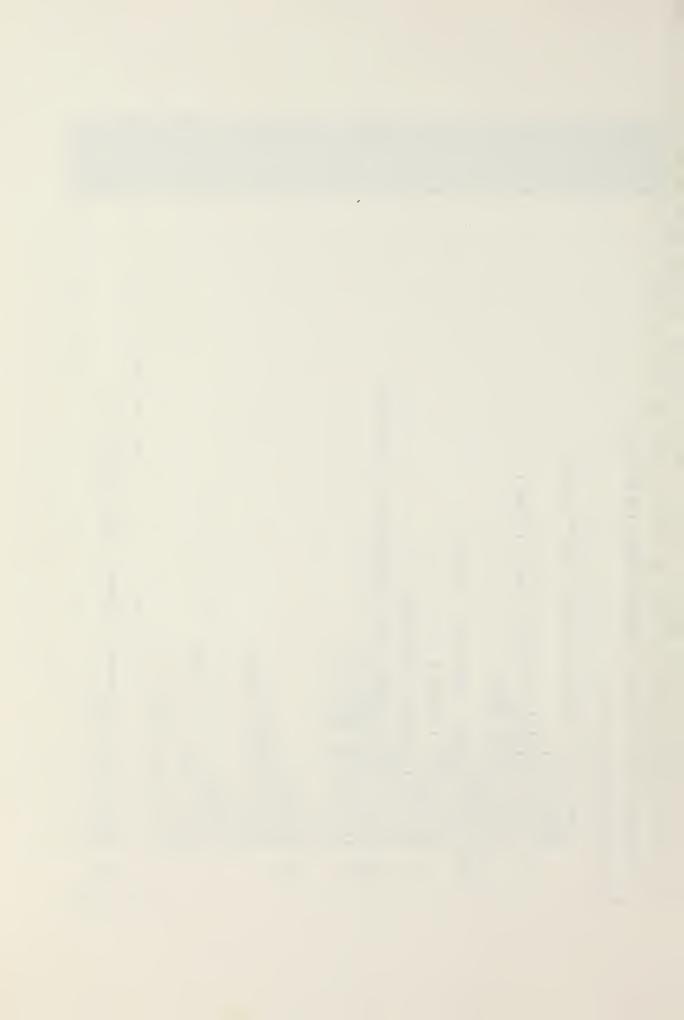
OO READ(5,1004) M, II JJ,MTVP,TEM,KK

IF (KK.EQ.0) KK=1

20 IF (KK.EQ.0) KK=1

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DIMENSION EMUL(4,5), IE(5), IX(4)

CCGMMON/GCONT/NUMNP, N & AR(20), NELTYP, NUMEL

NUME = NPAR(2)

NUMMAT = NPAR(3)

*** READ MATERIAL PROPERTIES

DO 60 M=1, NUMMAT

READ(5, 1010) MAT, NT

FORMAT(215)

IF(NT & 60 0) NT=1

NTC=2* NT

DO 50 K=1, NTC

READ(5, 1005) DUMMY

FORMAT(10A8)

CONTINUE
                                                                                                                                                                     ((EMUL(I,J),J=1,5),I=1,4
                                                                                                                                                                                                                                    E(I), I=1,4),KG
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30X, I5)
KG=1
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                                                                                                                                                                                                                                                                       IF(M.EQ.N) GO

IX(I) = IX(I) + KG

GO TO 150

IX(I) = IE(I) + CONTINUE

I = IX(I)

K = IX(2)

K = IX(3)

L = IX(4)

NUMEL = NUMEL + I

WRITE(10) N4, I

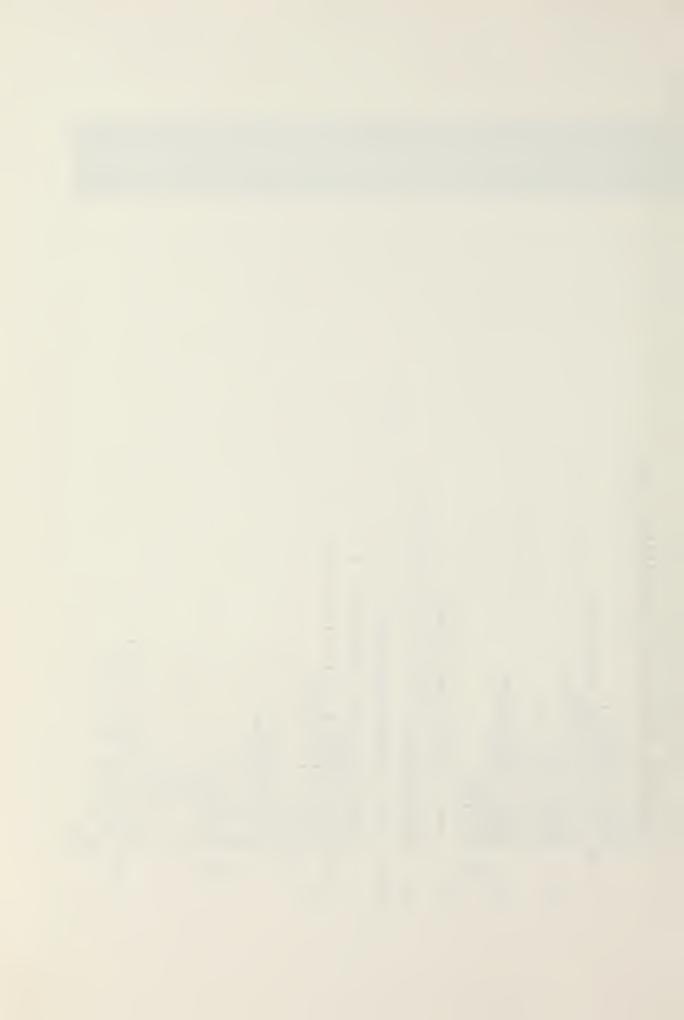
IF(N.EQ.NUME)

IF(N.EQ.NUME)

IF(N.EG.MUME)

IF(N.EG.MUME)

IF(N.EG.MUME)
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READ(5,1003)
FORMAT(5153)
IF(KG.EQ.0)
IF(M.EQ.N)
IF(M.EQ.N)
IX(I)=IX(I)+
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7X, I 8)
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KKK = JJ
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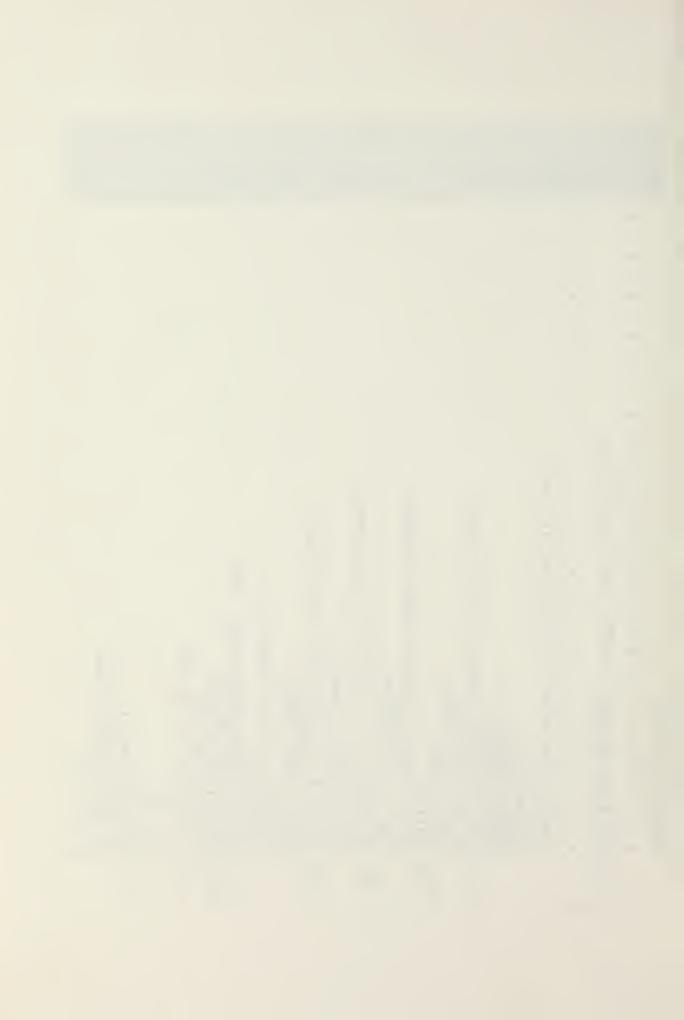
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COMMON/GCONT/NUMNP, NFAR(20), NELTYP, NUMEI
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** READ FAR(2)

** NUMMAT = NPAR(3)

** NUMMAT = NPAR(4)

** NEAD FORMAT ERIAL PROPERTIES

** PEAD FORMAT = NUMMAT

** ON TINUE

** READ CONTINUE

** READ ACCELERATION DUE TO GRAVITY

** READ ACCELERATION DUE TO GRAVITY

** READ ACCELERATION DUE TO GRAVITY

** READ (5,9002) DUMMY

** READ (5,9002) TINUE

** NEL = NEL + 1

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                                                                                     DIMENSION IY(7),IX(4)
COMMON/GCONT/NUMNP,NFAR(20),NELTYP,NUMEL
N4=4
ISTOP=0
NUME = NPAR(2)
NUMMAT = NPAR(3)
NMAT= 2*NUMMAT
READ MATERIAL PROPERTIES (DUMMY)
DO 10 N=1,NMAT
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     GO TO 162
GENERATION REQUIRED
DO 161 I=1,8
NP(I)=NP(I)+IINC
CONTINUE
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ELTYPE
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                                               END
SUBROUTINE SHELL
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WRITE(10) NB
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NUME=NPAR(2)
READ LOAD CASE CARD (DUMMY)
READ(5,1002) DUMMY
** READ BOUNDARY ELEMENT CARDS
N=0
N=0
N=0
IF(N.GE.NUME) RETURN
IF(K.GT.0) GO TO 200
GO TO 100
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|=N+(M2-M)/KK
|F(N,GE,NUME) RETURN
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                                                      NUMEL +1
) N4,NN,I,J,K,L
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                                          K=1 X(3)

L=1X(4)

NUMEL = NUMEL +1

NUMEL = 0.0 N4,NN,1

GO TO 500

WRITE (6,2005) MM

FORMAT (19HOCARD F

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IF (NN EQ.NUME) RE

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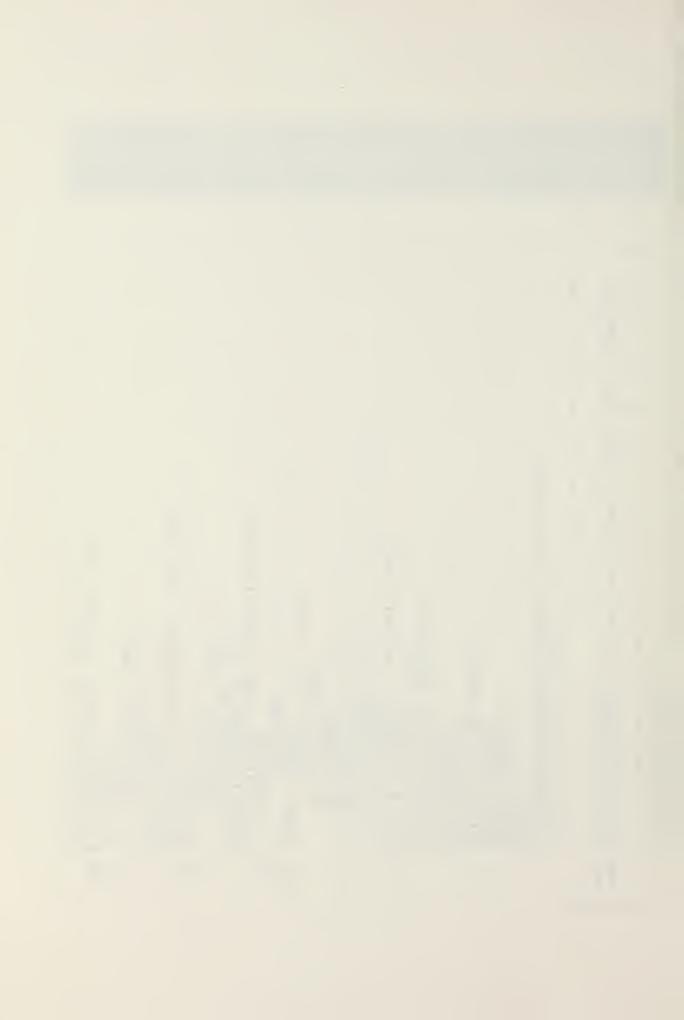


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N20=20
NSO=21=NPAR(3)
MUNMAT=NPAR(3)
NUMMAT=NPAR(4)
IF (MAXTP=NPAR(5)
NDLS=NPAR(5)
NDLS=NPAR(6)
IF (MAXNOD=EQ.8) NAXNOD=21
IF (MAXNOD=EQ.8) NAO=8
IF (MAXNOD=EQ.8) NAO=8
NOPSET=NPAR(8)
NOPSET=NPAR(8)
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NEAD(5,9006) INEL,IIN

FORMAT(15,35X,15)

FORMAT(1615)

IF(IINC-60.0) IINC=1

NEL=NEL+1

ML=INEL+1

IF(ML) 150,155,160

CALL ERROR(6)

NO GENERATION OF NODE
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, NUDISP, NVDISP, NWEISP
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ODE, NNCEST, NUDISP, NVDISP, NWCISP
IP, NPAR(20), NELTYP, NUMEL
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IDOF(I), I=1,6), NEGL, NEGNL, MODEX, NSTE
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2PSCALE KDISP, DMAG, KCCE
COMMON/KGUNT/NUMB, NPAR(20), NELTYP, NUMEL
DIMENSION NUMPT(1); XPT(1); YPT(1); NDISP, NVDISP
COMMON/GCONT/NUMNP, NPAR(20), NELTYP, NUMEL
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TO DETERMINE
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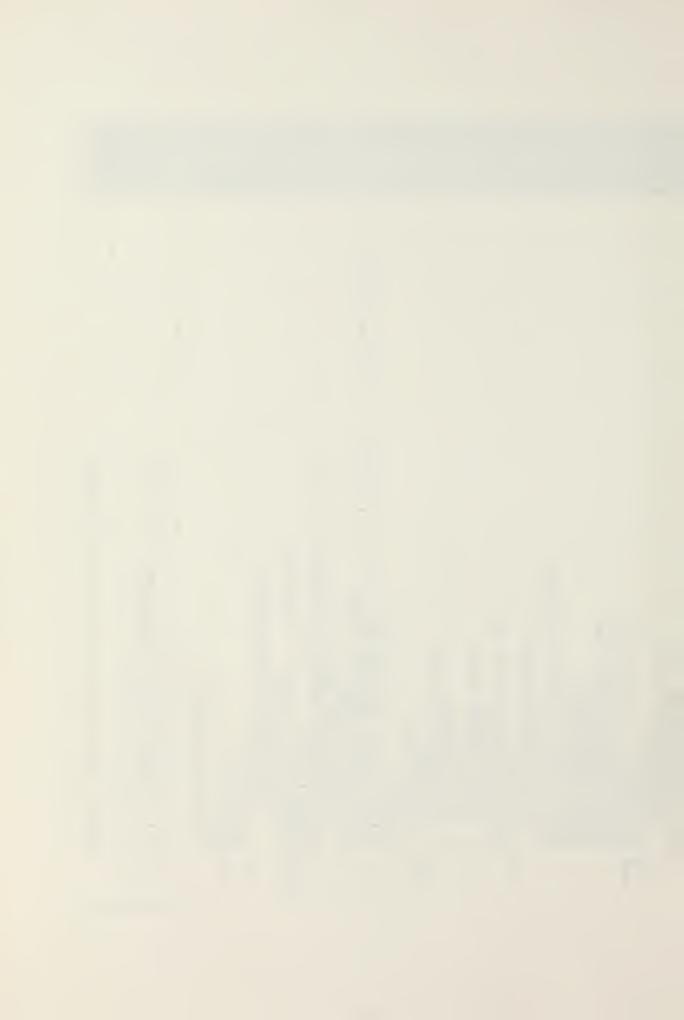
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  NUMMAT=NPAR(16)

N2=2
IF(NPAR(15).EQ.1) NCARD=2
IF(NPAR(15).EQ.3) NCARD=3
IF(NPAR(15).EQ.3) NCARD=3
IF(NPAR(15).NE.2) GO TO 20
CARDNR=NPAR(15).NE.2) GO TO 20
CARDNR=NPAR(15).NCARD
IF(TEST.GT.0.1) NCARD=NCARD
NCARD=NCARD+2
CONTINUE
READ MATERIAL PROPERTIES
DO 45 I=1,NUMMAT
DO 50 J=1,NUMMAT
CONTINUE
READ CONTINUE
CONTINUE
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RE
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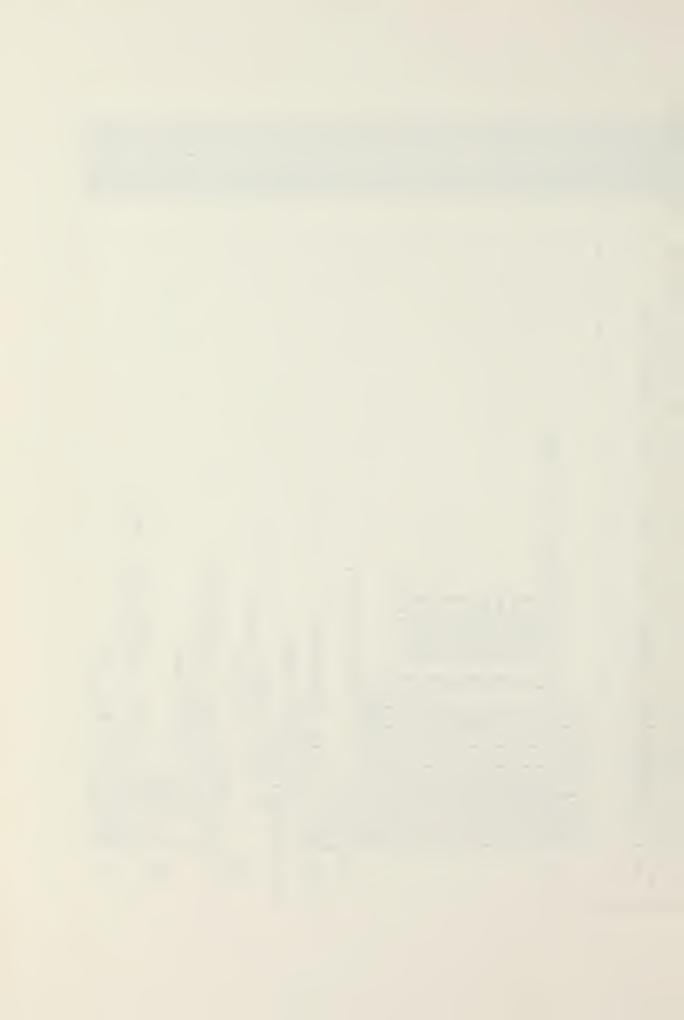
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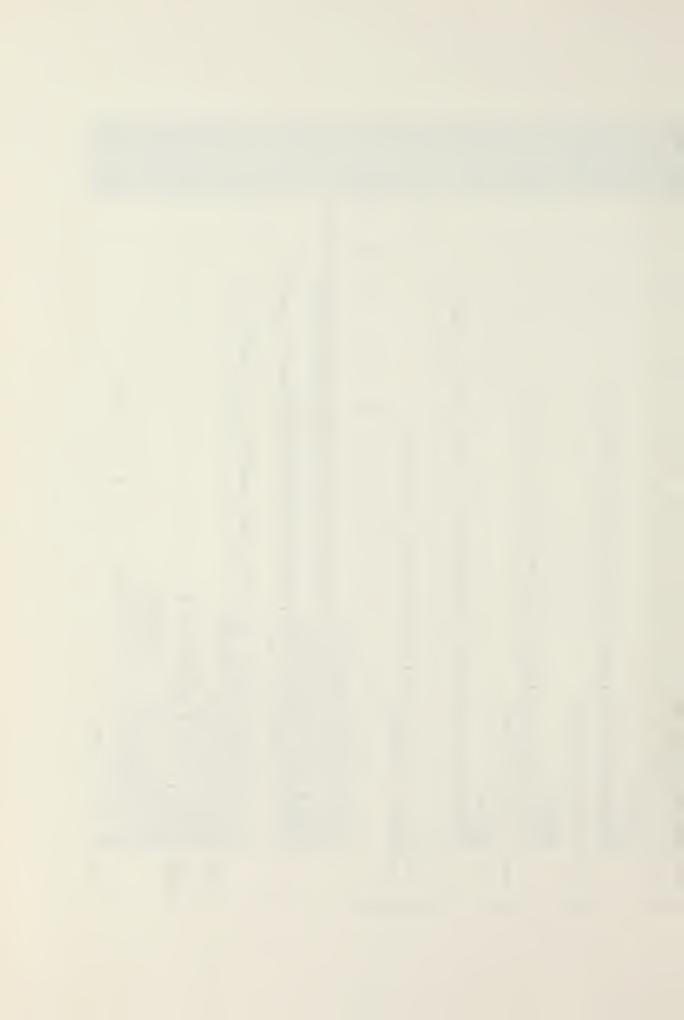
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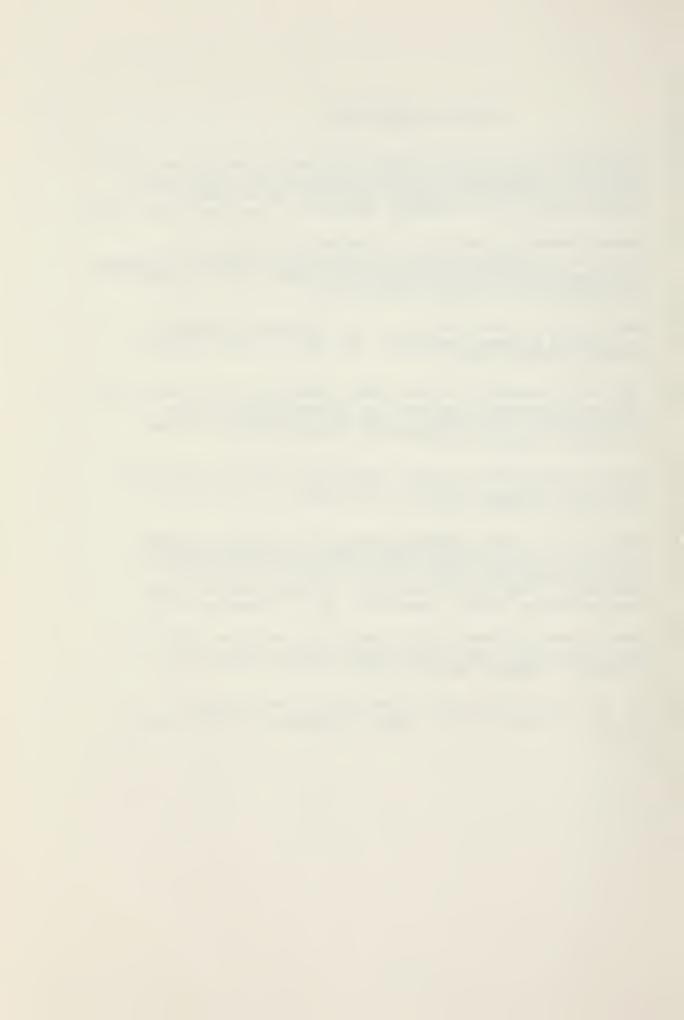
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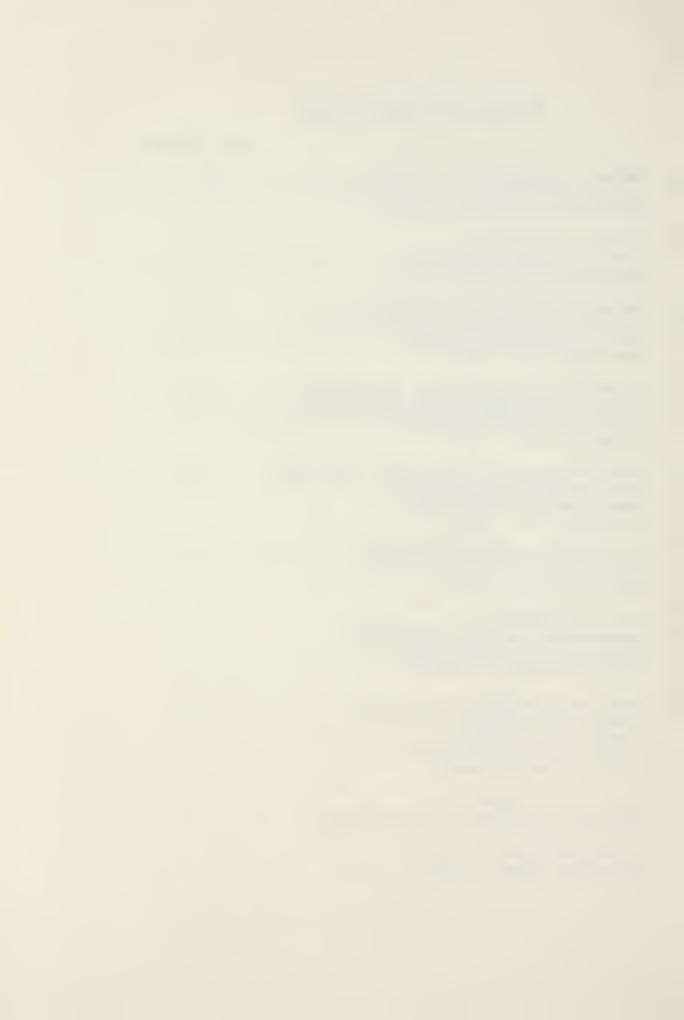
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